

Branes, Quivers and BPS algebras

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3.10. Recapitulation

- We have argued that the derived category of coherent sheaves form a good model of branes and their bound states with morphisms encoding the spectrum of open strings.
- Studying morphisms in our category, we derived a class of supersymmetric quantum mechanics labelled by a framed quiver with potential.
- We have seen that after a deformation by Ω -background, the supersymmetric quantum mechanics describing the low energy behavior of n D0-branes bound to a D2-, D4- and D6-brane has vacua labelled by $1d$, $2d$ and $3d$ partitions respectively.
- Today, we are going to introduce an algebraic describing processes of bounding/separating D0-branes from a give bound-state. More concretely, we are going to see how to use the correspondence $M(n+1, n)$ from yesterday to construct a module structure on the space of our BPS vacua.

4. Modules from correspondences

4.1. Rising and lowering generators

- The goal is to define a geometric action of a two copies of the cohomological Hall algebra (rising and lowering generators) increasing and decreasing the number of D0-branes.

[Nakajima (1984), Kontsevich-Soibelman (2010),...]

- In particular, we are now going to define

$$e_m : H_{U(1)^2}^*(M(n), \text{Crit}(W)) \rightarrow H_{U(1)^2}^*(M(n+1), \text{Crit}(W))$$

$$f_m : H_{U(1)^2}^*(M(n+1), \text{Crit}(W)) \rightarrow H_{U(1)^2}^*(M(n), \text{Crit}(W))$$

where $M(n) = \mathcal{M}(n)/GL(n)$ and $\mathcal{M}(n)$ is the space of stable quiver representations

$$(B_1, B_2, B_3, I) \quad (B_1, B_2, B_3, I, J) \quad (B_1, B_2, B_3, I, J_1, J_2)$$

for the framed moduli space associated to D2, D4 and D6 respectively and the circular node of dimension n .

4.2. Affine Yangian of \mathfrak{gl}_1

- Introducing generators

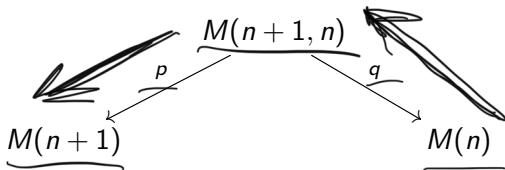
$$\psi_{m+n} = [e_m, f_n]$$

the triple e_n, f_n, ψ_n can be shown to satisfy relations of (shifted) \mathfrak{gl}_1 affine Yangian (see e.g. [Tymbaliuk (2014)]) and different choices of framings lead to its different representations [MR-Soibelman-Yang-Zhao (2020)].

- In this section, we are going to construct such representations for the three elementary framings.
- If we started from a different geometry than \mathbb{C}^3 , we would likely discover the Quiver Yangians from [Li-Yamazaki (2020)] and their representations [Galakhov-Li-Yamazaki (2021)].

4.4. Nakajima's rising and lowering operators

- At the end of the last lecture, we defined a correspondence



- Starting with $\alpha \in H_{U(1)^2}^*(M(n), \text{Crit}(W))$, we can now define

$$e_0 \alpha = p_*(q^*(\alpha))$$

by pulling it back by q and pushing forward by q and obtain an element in $H_{U(1)^2}^*(M(n+1), \text{Crit}(W))$.

- Reversing the order of the two maps, we have

$$f_0 \alpha = q_*(p^*(\alpha))$$

- Utilizing the tautological line bundle, we can define

$$e_m \alpha = p_*(c_1(L^m) \wedge q^*(\alpha))$$

$$f_m \alpha = q_*(c_1(L^m) \wedge p^*(\alpha))$$

4.7. Fixed-points basis

- Remember that we have an isomorphism of equivariant cohomologies of the form

$$\begin{aligned} \bigoplus_{\lambda} H^*(\lambda) & \rightarrow H_{U(1)^2}^*(M(n), \text{Crit}(W)) \\ \bigoplus_{\lambda \in F_n} \mathbb{C}[\epsilon_1, \epsilon_2]|\lambda\rangle & \rightarrow H_{U(1)^2}^*(M(n), \text{Crit}(W)) \\ \bigoplus_{(\lambda, \lambda + \square) \in F_{n+1, n}} \mathbb{C}[\epsilon_1, \epsilon_2]|\lambda, \lambda + \square\rangle & \rightarrow H_{U(1)^2}^*(M(n+1, n), \text{Crit}(W)) \end{aligned}$$

with F_n being the fixed-point set of $M(n)$ and $F_{n+1, n}$ the fixed-point set of $M(n+1, n)$.

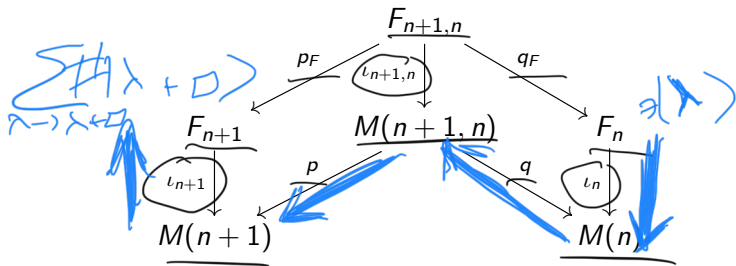
- We also have the embeddings of fixed points

$$\begin{aligned} \iota_{\lambda} & : \lambda \hookrightarrow M(n) \text{ for } \lambda \in F_n \\ \iota_{\lambda, \lambda + \square} & : \lambda \hookrightarrow M(n+1, n) \text{ for } \lambda \in F_{n+1, n} \end{aligned}$$

- Pushing forward generators $|\lambda\rangle \in H_{U(1)^2}^*(\lambda)$ and $|\lambda, \lambda + \square\rangle \in H_{U(1)^2}^*(\lambda, \lambda + \square)$ by these maps thus produces a natural fixed-point basis of $H_{U(1)^2}^*(M(n), \text{Crit}(W))$ and $H_{U(1)^2}^*(M(n+1, n), \text{Crit}(W))$ respectively.

4.8. Action in fixed-points basis

- We can now consider the following diagram



- Using the above correspondence, we can now find the action of e_n, f_n in the fixed-point basis given by $|\lambda\rangle \in H_{U(1)^2}^*(\lambda)$ as

$$\begin{aligned}
 e_m |\lambda\rangle &= \iota_{n+1*}^{-1} \circ p_* \circ c_1(L^m) \wedge q^* \circ \iota_{n*} |\lambda\rangle \\
 f_m |\lambda + \square\rangle &= \iota_{n*}^{-1} \circ q_* \circ c_1(L^m) \wedge p^* \circ \iota_{n+1*} |\lambda + \square\rangle
 \end{aligned}$$

4.9. Atiyah-Bott localization formula

- Let λ be a fixed point in $M(n)$, then we can invert the push-forward of the embedding $\iota_\lambda : \lambda \hookrightarrow M(n)$ as

$$\iota_{\lambda*}^{-1} = \frac{\iota_\lambda^*}{e_{U(1)^2}(T_\lambda^* M(n))}$$

where $T_\lambda^* M(n)$ is the tangent space of $M(n)$ at λ and $e_{U(1)^2}(\cdot)$ encodes its weights as a $U(1)^2$ representation.

- More concretely, $T_\lambda^* M(n)$ splits into the direct sum of $U(1)^2$ representations

$$T_\lambda^* M(n) = \bigoplus_{\alpha=1}^{\dim M(n)} \mathbb{C}_{\epsilon_\alpha}$$

where $U(1)^2$ acts on $\mathbb{C}_{\epsilon_\alpha}$ as

$$z \rightarrow e^{i\epsilon_\alpha} z$$

- The character is then given by the product

$$e_{U(1)^2}(T_\lambda^*(M)) = \prod_{i=1}^{\dim M(n)} \epsilon_\alpha$$

4.10. Towards explicit formula

- Let us now sketch the calculation for $e_0|\lambda\rangle$.

- Commuting the push-forward maps

$$\iota_{n+1*}^{-1} \circ p_* \circ q^* \circ \iota_{n*} |\lambda\rangle = p_{F*} \circ \iota_{n+1,n*}^{-1} \circ q^* \circ \iota_{n*} |\lambda\rangle$$

- The Atiyah-Bott localization formula leads to

$$= \sum_{(\mu+\square, \mu) \in F_{n+1, n}} \frac{p_{F*} \circ i_{\mu+\square, \mu}^* \circ q^* \circ \iota_{\lambda*}}{e_{U(1)^3}(T_{\mu+\square, \mu}^* M(n+1, n))} |\lambda\rangle$$

- Commuting the pull-back maps gives

$$= \sum_{(\mu+\square, \mu) \in F_{n+1, n}} \frac{p_{F*} \circ q_{\mu+\square, \mu}^* \circ \iota_{\mu*}^* \circ \iota_{\lambda*}}{e_{U(1)^3}(T_{\mu+\square, \mu}^* M(n+1, n))} |\lambda\rangle$$

- Using the Atiyah-Bott localization formula again

$$\sum_{(\mu+\square, \mu) \in F_{n+1, n}} \frac{e_{U(1)^3}(T_{\mu}^* M(n))}{e_{U(1)^3}(T_{\mu+\square, \mu}^* M(n+1, n))} p_{F*} \circ q_{\mu+\square, \mu}^* \circ \iota_{\mu*}^{-1} \circ \iota_{\lambda*} |\lambda\rangle$$

- The composition of $\iota_{\mu^*}^{-1}$ with ι_{λ^*} vanishes unless $\lambda = \mu$ and

$$= \sum_{(\lambda+\square, \lambda) \in F_{n+1, n}} \frac{e_{U(1)^2}(T_\lambda^* M(n))}{e_{U(1)^2}(T_{\lambda+\square, \lambda}^* M(n+1, n))} \rho_{F^*} \circ q_{\lambda+\square, \lambda}^* |\lambda\rangle$$

$\lambda \rightarrow \lambda + \square, \lambda$
 \downarrow
 $\lambda + \square$

leading to the final expression

$$= \sum_{(\lambda+\square, \lambda) \in F_{n+1, n}} \frac{e_{U(1)^2}(T_\lambda^* M(n))}{e_{U(1)^2}(T_{\lambda+\square, \lambda}^* M(n+1, n))} |\lambda + \square\rangle$$

- Analogously for other operators, the final formulas read

$$e_m |\lambda\rangle = \sum_{(\lambda, \lambda+\square) \in F_{n+1, n}} \frac{\epsilon_\square^m e_{U(1)^2}(T_\lambda^* M(n))}{e_{U(1)^2}(T_{\lambda+\square, \lambda}^* M(n+1, n))} |\lambda + \square\rangle$$
$$\underline{f_m} |\lambda + \square\rangle = \sum_{(\lambda, \lambda+\square) \in F_{n+1, n}} \frac{\epsilon_\square^m e_{U(1)^2}(T_{\lambda+\square}^* M(n+1))}{e_{U(1)^2}(T_{\lambda+\square, \lambda}^* M(n+1, n))} |\lambda\rangle$$

4.11. Character of the tangent space

- At a given fixed point, the vector space \mathbb{C}^n (and its dual) decomposes into weights according to the Young diagram

$$V_\lambda = \bigoplus_{\square \in \lambda} \mathbb{C}_{\epsilon_\square} \quad V_\lambda^* = \bigoplus_{\square \in \lambda} \mathbb{C}_{-\epsilon_\square}$$

$\square \mapsto \mathbb{C}_0 + \mathbb{C}_{\epsilon_1} + \mathbb{C}_{\epsilon_2}$

- The tangent space at a point λ is then given by the cohomology of the (equivariant) tangent complex

$$V_\lambda^* \otimes V_\lambda \xrightarrow{([B_i, \xi], \xi^I, \xi^{-1} J)} V_\lambda^* \otimes V_\lambda \otimes (\mathbb{C}_{\epsilon_1}^* + \mathbb{C}_{\epsilon_2}^* + \mathbb{C}_{\epsilon_3}^*) + V_\lambda + V_\lambda \otimes \mathbb{C}_\epsilon^*$$

B_1, B_2, B_3, I, J

- As a $U(1)^2$ representation, it decomposes as

$$T_\lambda = (\mathbb{C}_{\epsilon_1}^* + \mathbb{C}_{\epsilon_2}^* + \mathbb{C}_{\epsilon_3}^* - 1) \otimes V_\lambda \otimes V_\lambda^* + V_\lambda + V_\lambda \otimes \mathbb{C}_\epsilon^*$$

- Using $\mathbb{C}_\epsilon \otimes \mathbb{C}_{\tilde{\epsilon}} = \mathbb{C}_{\epsilon + \tilde{\epsilon}}$ we can simplify the above expression into a sum of $\mathbb{C}_{\epsilon_\alpha}$ terms and write the character as the product of $U(1)^2$ weights

$$\prod_{\alpha} \epsilon_\alpha$$

- Computation of the tangent space to the correspondence at $(\lambda + \square, \lambda)$ is slightly more complicated (see e.g. [Nakajima (1984)]). It decomposes as a $U(1)^2$ representation as

$$T_\lambda + T_{\lambda+\square} - N_{\lambda+\square, \lambda}$$

where

$$N_{\lambda+\square, \lambda} = (\mathbb{C}_{\epsilon_1}^* + \mathbb{C}_{\epsilon_2}^* + \mathbb{C}_{\epsilon_3}^* - 1) \otimes V_\lambda \otimes V_{\lambda+\square}^* + V_\lambda + V_{\lambda+\square}^* \oplus \mathbb{C}_\epsilon^*$$

is the decomposition into the $U(1)^2$ representation of the normal bundle of $M(n+1, n)$ inside $M(n+1) \times M(n)$ at $(\lambda + \square, \lambda)$.

- As a result, we can write

$$e_m|\lambda\rangle = \sum_{(\lambda, \lambda+\square) \in F_{n+1, n}} \epsilon_\square^m e_{U(1)^2}(N_{\lambda+\square, \lambda} - T_{\lambda+\square})|\lambda + \square\rangle$$

$$f_m|\lambda + \square\rangle = \sum_{(\lambda, \lambda+\square) \in F_{n+1, n}} \epsilon_\square^m e_{U(1)^2}(N_{\lambda+\square, \lambda} - T_\lambda)|\lambda\rangle$$

4.12. D2-brane and the vector representation

- Let us now explicitly evaluate the above expressions in the case of the D2-moduli space.
- According to the above formulas, $f_m |n+1\rangle$ is given by

$$(n\epsilon_1)^m \frac{e(V_n \otimes V_{n+1}^* \otimes (C_{\epsilon_1}^* + C_{\epsilon_2}^* + C_{\epsilon_3}^* - 1)) + V_n + (C_{\epsilon_1+\epsilon_2}^* + C_{\epsilon_1+\epsilon_3}^*) \otimes V_{n+1}^*}{e(V_n \otimes V_n^* \otimes (C_{\epsilon_1}^* + C_{\epsilon_2}^* + C_{\epsilon_3}^* - 1)) + V_n + (C_{\epsilon_1+\epsilon_2}^* + C_{\epsilon_1+\epsilon_3}^*) V_n^*} |n\rangle$$

$\prod_{i=1}^m (-n\epsilon_1 + (i-1)\epsilon_1 - \epsilon_1)$
 $\prod_{i=1}^m (-n\epsilon_1 - \epsilon_1 - \epsilon_2) (-n\epsilon_1 - \epsilon_1 - \epsilon_3)$

$$(n\epsilon_1)^m (n\epsilon_1 - \epsilon_3)(n\epsilon_1 - \epsilon_2) \prod_{i=1}^m \frac{(n\epsilon_1 - (i-1)\epsilon_1 + \epsilon_1)(n\epsilon_1 - (i-1)\epsilon_1 + \epsilon_2)(n\epsilon_1 - (i-1)\epsilon_1 + \epsilon_3)}{n\epsilon_1 - (i-1)\epsilon_1} |n\rangle$$

- Analogously $e_m |n\rangle$ is given by

$$(n\epsilon_1)^m \frac{e(V_n \otimes V_{n+1}^* \otimes (C_{\epsilon_1} + C_{\epsilon_2} + C_{\epsilon_3} - 1)) + V_n + (C_{\epsilon_1+\epsilon_2} + C_{\epsilon_1+\epsilon_3}) \otimes V_{n+1}^*}{e(V_{n+1} \otimes V_{n+1}^* \otimes (C_{\epsilon_1}^* + C_{\epsilon_2}^* + C_{\epsilon_3}^* - 1)) + V_{n+1} + (C_{\epsilon_1+\epsilon_2}^* + C_{\epsilon_1+\epsilon_3}^*) V_{n+1}^*} |n+1\rangle$$

$$(n\epsilon_1)^m \prod_{i=1}^{n+1} \frac{n\epsilon_1 - (i-1)\epsilon_1}{(n\epsilon_1 - (i-1)\epsilon_1 - \epsilon_1)(n\epsilon_1 - (i-1)\epsilon_1 - \epsilon_2)(n\epsilon_1 - (i-1)\epsilon_1 - \epsilon_3)} |n+1\rangle$$

- We can now simplify the products as

$$\begin{aligned}
 \uparrow f_m |n+1\rangle &= (n+1)(n\epsilon_1)^n \prod_{i=1}^{n+1} ((n+1-i)\epsilon_1 - \epsilon_2)((n+1-i)\epsilon_1 - \epsilon_3) |n\rangle \\
 \downarrow e_m |n\rangle &= -\frac{1}{\epsilon_1} (n\epsilon_1)^n \prod_{i=1}^{n+1} \frac{1}{((n+1-i)\epsilon_1 - \epsilon_2)((n+1-i)\epsilon_1 - \epsilon_3)} |n+1\rangle
 \end{aligned}$$

- Let us introduce

$$A_k = \prod_{i=1}^k \frac{1}{((k+1-i)\epsilon_1 - \epsilon_2)((k+1-i)\epsilon_1 - \epsilon_3)}$$

and renormalize

$$|\tilde{m}\rangle = \prod_{k=1}^m A_k |m\rangle$$

- In terms of the renormalized basis, we have

$$\begin{aligned}
 \underline{f_n |m+1\rangle} &= (m+1)(m\epsilon_1)^n |m\rangle \\
 e_n |m\rangle &= -\frac{1}{\epsilon_1} (m\epsilon_1)^n |m+1\rangle
 \end{aligned}$$

- If we identify

$$\begin{aligned}
 f_n |n+1\rangle &= (\epsilon_1 z \partial)^n \partial z^{n+1} \\
 &= (n+1) (\epsilon_1 z \partial)^n z^n \\
 &= (n+1) (\epsilon_1 z)^n z^n \\
 |m\rangle &= z^m = (n+1) (\epsilon_1 z)^n |n\rangle
 \end{aligned}$$

the above action factors through

$$\begin{array}{l}
 \uparrow \\
 f_n \rightarrow (\epsilon_1 z \partial)^n \partial \\
 \downarrow \\
 e_n \rightarrow \frac{1}{\epsilon_1} z (\epsilon_1 z \partial)^n
 \end{array}$$

acting on $\mathbb{C}[z]$.

- We have ended up with a geometric construction of so-called vector representation of the 1-shifted affine Yangian.

4.13. D4-brane and the Fock representation

- One can perform the same calculation for the D4-brane framing and obtain the Fock representation of the affine Yangian. Instead of doing the algebra let us simply state the result.
- Let us introduce an associative algebra

$$[J_m, J_n] = -\frac{1}{\epsilon_1 \epsilon_2} m \delta_{m, -n}$$

- This algebra is known as the $\widehat{\mathfrak{gl}}_1$ Kac-Moody algebra, the \mathfrak{gl}_1 current algebra or the Heisenberg vertex operator algebra.
- It turns out that this algebra can be given a structure of a vertex operator algebra. Generally, configurations of D4-branes are always expected to lead to a vertex operator algebra leading to an interesting interplay between the theory of VOAs and the geometry of divisors in Calabi-Yau threefolds. [\[Procházka-MR \(2018\)\]](#)

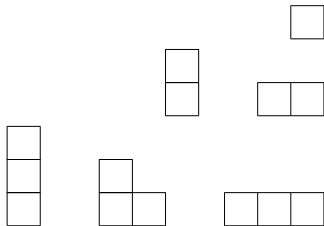
- $\widehat{\mathfrak{gl}}_1$ admits a class of highest-weight modules generated by the action of negative modes J_n on $|\mu\rangle$ satisfying

$$J_0|\mu\rangle = \mu|\mu\rangle, \quad J_m|\mu\rangle = 0, \quad \text{for } m > 0$$

- The modules are generated by

$$\begin{aligned}
 & J_{-1}|\mu\rangle \\
 & J_{-1}^2|\mu\rangle, \quad J_{-2}|\mu\rangle \\
 & J_{-1}^3|\mu\rangle, \quad J_{-1}J_{-2}|\mu\rangle, \quad J_{-3}|\mu\rangle
 \end{aligned}$$

- Note also that these are in correspondence with 2d partitions



- An alternative basis of the Yangian is formed by $[e_1, e_2]$ and

$$\tilde{J}_{-n} = \frac{1}{(m-1)!} \text{ad}_{e_1}^{m-1} e_0, \quad \tilde{J}_n = \frac{1}{(m-1)!} \text{ad}_{f_1}^{m-1} f_0$$

$J_{-1} = e_0, J_{-2} = [e_1, e_0], J_{-3} = [e_1, [e_1, e_0]], \dots$

- The geometric action constructed above factors through

$$Y_{0,0,1} : \underline{\tilde{J}_n} \rightarrow J_n$$

$$Y_{0,0,1} : \underline{[e_1, e_2]} \rightarrow \frac{\epsilon_1^2 \epsilon_2^2}{3} \sum_{k,m=-\infty}^{\infty} : J_{-m-k-2} J_m J_k : + \frac{\epsilon_1 \epsilon_2 \epsilon_3}{2} \sum_{m=1}^{\infty} m J_{-m-1} J_{m-1}$$

acting on the above Fock module for $\mu = 0$.

- It is also possible to recover the general μ by introducing an equivariant parameter associated to the $GL(1)$ action of the framing node. This refinement turns out to be essential for understanding representations associated to more complicated configurations of D4-branes as we are going to sketch in the next section.

4.14. D6-brane and the MacMahon

- Analogously, one can construct a representation of a -1 -shifted affine Yangian on a vector space labeled by 3d partitions associated to the D6-brane framing. It is straightforward to find explicit relations and recover the formulas from [\[MR-Soibelman-Yang-Zhao \(2020\)\]](#). Restricting to the non-shifted Yangian, this module is conjecturally equivalent to the module constructed algebraically in [\[Feigin-Jimbo-Miwa-Mukhin \(2012\), Procházka \(2015\)\]](#).

5. Cherednik and \mathcal{W} algebras

5.1. Affine Yangian

- e_m, f_m, ψ_m for D4-branes satisfy relations of the \mathfrak{gl}_1 affine Yangian [Schiffmann-Vasserot (2012), Maulik-Okounkov (2012)]:

$$\psi_{i+j} = [e_i, f_j] \quad [\psi_i, \psi_j] = 0$$

$$0 = [e_{i+3}, e_j] - 3[e_{i+2}, e_{j+1}] + 3[e_{i+1}, e_{j+2}] - [e_i, e_{j+3}] \\ + \sigma_2[e_{i+1}, e_j] - \sigma_2[e_i, e_{j+1}] - \sigma_3\{e_i, e_j\}$$

$$0 = [f_{i+3}, f_j] - 3[f_{i+2}, f_{j+1}] + 3[f_{i+1}, f_{j+2}] - [f_i, f_{j+3}] \\ + \sigma_2[f_{i+1}, f_j] - \sigma_2[f_i, f_{j+1}] + \sigma_3\{f_i, f_j\}$$

$$0 = [\psi_{i+3}, e_j] - 3[\psi_{i+2}, e_{j+1}] + 3[\psi_{i+1}, e_{j+2}] - [\psi_i, e_{j+3}] \\ + \sigma_2[\psi_{i+1}, e_j] - \sigma_2[\psi_i, e_{j+1}] - \sigma_3\{\psi_i, e_j\}$$

$$0 = [\psi_{i+3}, f_j] - 3[\psi_{i+2}, f_{j+1}] + 3[\psi_{i+1}, f_{j+2}] - [\psi_i, f_{j+3}] \\ + \sigma_2[\psi_{i+1}, f_j] - \sigma_2[\psi_i, f_{j+1}] + \sigma_3\{\psi_i, f_j\}$$

$$[\psi_0, e_i] = [\psi_0, f_i] = [\psi_1, e_i] = [\psi_1, f_i] = 0$$

$$[\psi_2, e_i] = 2e_i \quad [\psi_2, f_i] = -2f_i$$

$$\text{Sym}_{i,j,k}[e_i, [e_j, e_k]] = 0 \quad \text{Sym}_{i,j,k}[f_i, [f_j, f_k]] = 0$$

- Its subalgebras generated by e_m restricted to $m \geq k$ together with all f_m, ψ_m are called k -shifted affine Yangians.
- With a little bit of work, one can also introduce shifted Yangians with negative shift $k < 0$ but let us not go into details. [MR-Soibelman-Yang-Zhao (2020)]
- More complicated representations of the \mathfrak{gl}_1 affine Yangian can be obtained by utilizing the coproduct

$$\Delta : \mathcal{Y} \rightarrow \mathcal{Y} \otimes \mathcal{Y}$$

given by formulas

$$\Delta : J_n \rightarrow J_n \otimes \mathbb{1} + \mathbb{1} \otimes J_n$$

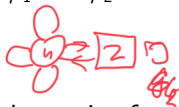
$$\Delta : [e_2, e_1] \rightarrow [e_2, e_1] \otimes \mathbb{1} + \mathbb{1} \otimes [e_2, e_1] + \epsilon_1 \epsilon_2 \epsilon_3 \sum_{m=1}^{\infty} m J_{-m-1} \otimes J_{m-1}$$

[Schiffmann-Vasserot (2012), Maulik-Okounkov (2012)]

5.2. Corner vertex operator algebras

- Let us first compose the coproduct with the two Fock representations $Y_{0,0,1}$ acting on the Fock spaces $\mathcal{F}_{\mu_1} \otimes \mathcal{F}_{\mu_2}$:

$$(Y_{0,0,1} \otimes Y_{0,0,1}) \circ \Delta(t)$$



- The states of $\mathcal{F}_{\mu_1} \otimes \mathcal{F}_{\mu_2}$ are in correspondence with a pair of partitions that are in turn in correspondence with fixed points of the quiver moduli with rank-two framing if we introduce equivariant parameters μ_1, μ_2 associated to the Cartan of $GL(2)$ acting on the framing node.
- This is exactly the representation one gets from correspondences! [[Schiffmann-Vasserot \(2012\)](#), [Maulik-Okounkov \(2012\)](#), [Yang-Zhao \(2016\)](#)]

- One can also show that the above map produces only a subalgebra of the tensor product of $\widehat{\mathfrak{gl}}_1$ Kac-Moody algebras known as the Virasoro algebra tensored with a single copy of the $\widehat{\mathfrak{gl}}_1$ Kac-Moody algebra generated by L_m, J_n such that

$$[J_m, J_n] = -\frac{2}{\epsilon_1 \epsilon_2} \delta_{m, -n}$$

$$[L_m, J_n] = -n J_{m+n}$$

$$[L_m, L_n] = (m - n) L_{m+n} + \frac{1}{6} \left(7 + 3 \left(\frac{\epsilon_1}{\epsilon_2} + \frac{\epsilon_2}{\epsilon_1} \right) \right) n (n^2 - 1) \delta_{m, -n}$$

- The highest weight state then satisfies

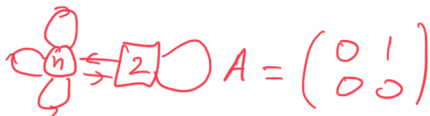
$$J_m |\mu_1, \mu_2\rangle = L_m |\mu_1, \mu_2\rangle = 0, \quad \text{for } m > 0$$

and is an eigenstate of J_0, L_0 with eigenvalues depending on μ_1, μ_2 .

- For special values of μ_1, μ_2 , the above-constructed module is not irreducible. For example, specializing μ_1, μ_2 such that $J_0|\mu_1, \mu_2\rangle = L_0|\mu_1, \mu_2\rangle = 0$, we can define an irreducible module by further imposing

$$L_{-1}|\mu_1, \mu_2\rangle = 0$$

- This module has a geometric construction coming from turning on the Higgs vev on D4-branes!
[\[Chuang-Creutzig-Diaconescu-Soibelman \(2019\)\]](#)



- One can proceed with a construction of more complicated algebras associated to a generic configuration of D4-branes by using the coproduct $N_1 + N_2 + N_3 - 1$ times and then composing with

$$Y_{1,0,0}^{\oplus N_1} \otimes Y_{0,1,0}^{\oplus N_2} \otimes Y_{0,0,1}^{\oplus N_3}$$



leading to a class of corner vertex operator algebras [Gaiotto-MR (2017)] acting on the tensor product of $N_1 + N_2 + N_3$ Fock modules [Bershtein-Feigin-Merzon (2015), Litvinov-Spodyneiko (2016), Prochazka-MR (2018)].

- These modules have a geometric construction coming from intersecting D4-branes! [MR-Soibelman-Yang-Zhao (2018)]
- Turning on nilpotent Higgs vevs in general setting produces "pit" representations [Bershtein-Feigin-Merzon (2015), Gaiotto-MR (2017), Prochazka-MR (2017)] as shown in [Butson-MR (in progress)].



5.3. Cherednik algebras

- Let us finish with an exploration of a much-less-understood construction associated to more general configurations of D2-branes.
- Recall the elementary M2-brane representation $A_{1,0,0}$:

$$f_0 = \partial, \quad f_1 = \epsilon_1 z \partial^2, \quad f_2 = (\epsilon_1 z \partial)^2 \partial \quad e_0 = \frac{1}{\epsilon_1} z, \quad e_1 = z^2 \partial$$

- In the new basis, we have

$$\underbrace{J_n} \rightarrow \frac{1}{\epsilon_1} \underbrace{z^n} \quad \underbrace{[f_0, f_1]} \rightarrow \epsilon_1 \underbrace{\partial^2}$$

- We can now use the coproduct and compose it with $A_{1,0,0} \otimes A_{1,0,0}$ to obtain

$$\begin{aligned}
 \underline{J_n} &\rightarrow \frac{1}{\epsilon_1} (\underline{z_1^n + z_2^n}) && \sum z_1 \quad \sum \partial_1 \\
 \underline{[f_0, f_1]} &\rightarrow \epsilon_1 \partial_1^2 + \epsilon_1 \partial_2^2 + \epsilon_1 \epsilon_2 \epsilon_3 \sum_{m=1}^{\infty} m \frac{z_1^{-m-1}}{\epsilon_1} \frac{z_2^{m-1}}{\epsilon_1} \\
 &\rightarrow \epsilon_1 \partial_1^2 + \epsilon_1 \partial_2^2 + \frac{\epsilon_2 \epsilon_3}{\epsilon_1} \frac{2}{(z_1 - z_2)^2}
 \end{aligned}$$

- These expressions are known as a Dunkel representation of the Cherednik algebra associated to $\mathfrak{gl}(2)$. See e.g. the lecture notes [Opdam (2000)].

- Similarly, one can use the coproduct $N_1 + N_2 + N_3 - 1$ times and compose the result with

$$A_{1,0,0}^{\oplus N_1} \otimes A_{0,1,0}^{\oplus N_2} \otimes A_{0,0,1}^{\oplus N_3}$$

and obtain

$$\begin{aligned}
 t_{0,d} &= \epsilon_1^{-1} \sum_{i=1}^{n_1} z_i^d + \epsilon_2^{-1} \sum_{i=1}^{n_2} (z'_i)^d + \epsilon_3^{-1} \sum_{i=1}^{n_3} (z''_i)^d \\
 t_{2,0} &= \epsilon_1 \sum_{i=1}^{n_1} \partial_{z_i}^2 + \frac{\epsilon_2 \epsilon_3}{\epsilon_1} \sum_{i < j} \frac{2}{(z_i - z_j)^2} + \epsilon_1 \sum_{i,j} \frac{2}{(z'_i - z''_j)^2} + \\
 &\quad + \epsilon_2 \sum_{i=1}^{n_2} \partial_{z'_i}^2 + \frac{\epsilon_1 \epsilon_3}{\epsilon_2} \sum_{i < j} \frac{2}{(z'_i - z'_j)^2} + \epsilon_2 \sum_{i,j} \frac{2}{(z_i - z''_j)^2} \\
 &\quad + \epsilon_3 \sum_{i=1}^{n_3} \partial_{z''_i}^2 + \frac{\epsilon_1 \epsilon_2}{\epsilon_3} \sum_{i < j} \frac{2}{(z''_i - z''_j)^2} + \epsilon_3 \sum_{i,j} \frac{2}{(z_i - z'_j)^2}
 \end{aligned}$$

that is a three-parametric generalization of the Cherednik algebra (and Calogero-Moser system) [MR-Gaiotto (2020)].