Local and Global Optimization of Particle Locations on the Sphere: Models, Applications, Mathematical Aspects, and Computations

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Problem and Motivation

- 2 Geometry and Typical Results
- Some Questions of Interest
- 4 Local and Global Optimization: a Numerical Method
- 5 Computational Results
- 6 Highlights and Open Problems

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Problem:

• Global optimization of some objective function that depends on positions of small "particles", or "pores", or "traps", on the surface of a 3D domain:

min $\mathcal{H}(\mathbf{x}_1,\ldots,\mathbf{x}_N), \qquad \mathbf{x}_i \in \partial V, \qquad V \subset \mathbb{R}^3.$

• Example 1: Thomson problem



Motivation: Example 1, Thomson problem

- Example 1: Thomson problem
- Total Coulombic interaction energy:

$$\mathcal{H}_{C}(\mathbf{x}_{1},\ldots,\mathbf{x}_{N})=\sum_{i=1}^{N}\sum_{j=i+1}^{N}h(\mathbf{x}_{i},\mathbf{x}_{j})$$

• Pairwise energy function:

$$h(\mathbf{x}_i,\mathbf{x}_j) = rac{1}{|x_i - x_j|}$$

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Motivation: Example 2, Narrow Escape Problems

• Example 2: Chemical exchange through nuclear pores



- Example 2: Chemical exchange through nuclear pores
- Typical nucleus size: $\sim 6 \times 10^{-6}$ m; pore size $\sim 10^{-8}$ m.
- $\bullet\,\sim$ 2000 nuclear pore complexes in a typical nucleus
- mRNA, proteins, smaller molecules
- $\bullet\,\sim$ 1000 translocations per complex per second
- $\bullet~\text{Trap}$ separation $\sim 5 \times 10^{-7}~\text{m}$

A Narrow Escape Problem:

- Diffusion / Brownian motion;
- High passage rates;
- Well-separated small surface traps.

• Similar mechanisms for ion pumps, like Na^+-K^+ pumps, etc.



The setup:

- A Brownian particle confined in a domain $\Omega \in \mathbb{R}^3.$
- Initial position: $x \in \Omega$.
- Mean First Passage Time (MFPT): v(x).
- Domain boundary: $\partial \Omega = \partial \Omega_r$ (reflecting) $\cup \partial \Omega_a$ (absorbing).
- $\partial \Omega_a = \bigcup_{i=1}^N \partial \Omega_{\varepsilon_i}$: small absorbing traps (size $\sim \varepsilon$).

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Problem for the MFPT v = v(x) [Holcman, Schuss (2004)]:

$$\left\{ \begin{array}{ll} \bigtriangleup v = -\frac{1}{D} \,, \quad x \in \Omega \,, \\ v = 0, \quad x \in \partial \Omega_a; \quad \partial_n v = 0, \quad x \in \partial \Omega_r. \end{array} \right.$$

Average MFPT: $\bar{v} = \frac{1}{|\Omega|} \int_{\Omega} v(x) \, dx = \text{const.}$

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Asymptotic assumptions:

- D = const;
- Domain: a unit sphere;
- N equal traps of radius $\varepsilon \ll 1$.
- An asymptotic result for the average MFPT [A.C., M.Ward, R.Straube (2010)]:

$$ar{
u} \sim rac{|\Omega|}{4arepsilon DN} \left[1 + rac{arepsilon}{\pi} \log\left(rac{2}{arepsilon}
ight) + rac{arepsilon}{\pi} \left(-rac{9N}{5} + 2(N-2)\log 2 + rac{3}{2} + rac{4}{N} \mathcal{H}_{MFPT}
ight)
ight];$$

$$\mathcal{H}_{MFPT}(\mathbf{x}_1, \dots, \mathbf{x}_N) = \sum_{i=1}^N \sum_{j=i+1}^N h(\mathbf{x}_i, \mathbf{x}_j),$$

 $h(\mathbf{x}_i, \mathbf{x}_j) = rac{1}{|x_i - x_j|} - rac{1}{2} \log |x_i - x_j| - rac{1}{2} \log (2 + |x_i - x_j|)$

- Similar results exist for non-spherical domains, non-equal traps;
- An asymptotic formula for the actual MFPT v = v(x) is also known.

Motivation: Example 3, Power and Logarithmic Interactions

• General power pairwise interaction potentials, same particles:

$$\mathcal{H}_n(\mathbf{x}_1,\ldots,\mathbf{x}_N) = \sum_{i=1}^N \sum_{j=i+1}^N h(\mathbf{x}_i,\mathbf{x}_j), \qquad h(\mathbf{x}_i,\mathbf{x}_j) = |x_i - x_j|^{-n}.$$

• Logarithmic potential:

$$\mathcal{H}_{log}(\mathbf{x}_1,\ldots,\mathbf{x}_N) = -\sum_{i=1}^N \sum_{j=i+1}^N \log |x_i - x_j|.$$

• Various applications, including the study of vortex defects in a liquid crystal confined to a closed surface with spherical topology [*Bergersen et al (1994) and references therein*].

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min $\mathcal{H}(\mathbf{x}_1,\ldots,\mathbf{x}_N), \qquad \mathbf{x}_i \in \partial V, \qquad V \subset \mathbb{R}^3.$

- The vast majority of results pertain to the 2-sphere $\partial V = S^2$ ("spherical designs").
- Virtually all results describe optimal configurations of identical particles.
- In some works, scaling laws are derived for a fixed total trap area as $N \to \infty$.

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The global optimization problem: features and progress

- A high-dimensional problem; 2N degrees of freedom in \mathbb{R}^3 (2N 3 for S^2).
- No exact solutions except for cases with high symmetry, in particular, sphere in n > 3 dimensions [e.g., *Cohn & Kumar (2006)*];
- "Black box" software: standard approaches (genetic algorithms, simulated annealing, dynamical systems, etc.)
- Potential- and domain-specific software.
- In the literature, putative numerical global minima are presented; virtually no works discuss local minima [*Erber & Hockney (1996)*].

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Geometrical Features and Questions



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- A long-standing problem of "uniformly meshing" a sphere (or another domain).
- How does one distinguish two similar/close configurations?
 - Energy values themselves are insufficient.
 - Particularly important in symmetric domains.
- Universally optimal configurations holding for a wide class of potentials? [Spheres in \mathbb{R}^n : e.g., *Cohn & Kumar (2006)*.]

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Geometrical Features and Questions

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Figure 16. Results of a minimization of 500 particles interacting with a Coulomb potential, showing the appearance of scars.

- Coordination number c_i of a particle: number of neighbours (usually $c_i = 6$).
- Topological constraints: Euler's Theorem, V E + F = 2; can show that

$$\sum_i (6-c_i) = 12,$$

where $(6 - c_i)$ is the "topological charge".

Geometrical Features and Questions

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Figure 16. Results of a minimization of 500 particles interacting with a Coulomb potential, showing the appearance of scars.

- At least 12 particles with five-fold coordination.
- A scar: a cluster of particles where $c_i \neq 6$.
- For the same N, different configurations may or may not have different scar pictures.
- Applications: 2D matter; defects play an essential role in describing crystalline particle packings on the sphere.

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A. Cheviakov, W. Ridgway (UofS, Canada)

Optimal Particle Locations on the Sphere

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- How can one systematically compute local minima? $N \rightarrow N+1$?
- How many local minima can one expect for a given N and a given potential, typically?
- How do the energy spectra look?
- What is the comparative scar geometry for various local and global minima?
- The "simplest" domain: unit sphere. Not much is known!

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A Numerical Method for Local and Global Optimization



- Implemented mainly in Matlab.
- Start from N = 4: tetrahedron.

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• Starting configurations: Introduce, one by one, triangle middles. Remove redundant configurations.

- For each starting configuration, perform local optimization (C++).
- Remove redundant configurations.
- Remove saddle points (Maple).
- Repeat $N \rightarrow N+1$.

• Geometrical symmetries!

- Geometrical symmetries!
- Coordinate-invariant characteristics of a configuration: energy; pairwise distances; pairwise energies...

- Geometrical symmetries!
- Coordinate-invariant characteristics of a configuration: energy; pairwise distances; pairwise energies...
- Many details will be given in the next talk.

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• Number of locally optimal configurations found for the Coulomb potential.



• Relative Coulomb energy spectrum.

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• Number of locally optimal configurations found for the Logarithmic potential.



• Relative Logarithmic energy spectrum.

Image: A math a math



Number of locally optimal configurations found for the Inverse Square Law potential.

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• Relative Inverse Square Law energy spectrum.



Six local minima for the inverse square law, N = 60.

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Main findings

- Local and global minima and respective configurations of identical particles for Coulomb, Logarithmic, and Inverse Square Law potentials.
- Coordination numbers and energy spectra computed.
- No special scar picture characterizes global minima.
- Saddles consistently arise in numerical dynamical system-based local optimization; can be systematically excluded.

Ongoing & future work

- Computations for higher N.
- Similar computations for the MFPT potential.
- Local minima for non-equal interacting particles?

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Some Highlights and Open Problems



• Spherical trap configurations for 2N = 8 traps of two kinds with radius ratio 10. The global minimum of the average MFPT \bar{v} . (b), (c): nearby local minima [*C., Reimer, Ward (2012)*].

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