Narrow Escape and Narrow Capture Problems in Three Dimensions: Modeling, Analysis, Optimization of Trap Configurations

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PIMS Workshop on New Trends in Localized Patterns in PDEs

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Narrow Escape Problems, Mean First Passage Time (MFPT)

2 The Narrow Capture problem

3 Overview of some NE/NC/optimization work in the last years

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Narrow Escape Problems, Mean First Passage Time (MFPT)

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Overview of some NE/NC/optimization work in the last years

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Narrow escape problems

- A Brownian particle escapes from a bounded domain through small windows.
- Examples: Pores of cell nuclei; synaptic receptors on dendrites, ...



Image: A match the second s

- A Brownian particle escapes from a bounded domain through small windows.
- $\bullet\,$ Typical nucleus size: $\sim 6 \times 10^{-6}$ m
- $\bullet~\mbox{Pore size} \sim 10^{-8}~\mbox{m}$
- $\bullet\,\sim$ 2000 nuclear pore complexes in a typical nucleus
- mRNA, proteins, smaller molecules
- $\bullet\,\sim$ 1000 translocations per complex per second
- $\bullet~\text{Trap}$ separation $\sim 5 \times 10^{-7}~\text{m}$

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Continuum formulation



Figure 1: A Schematic of the Narrow Escape Problem in a 2-D and a 3-D domain.

Given:

- A Brownian particle confined in a domain $\Omega \in \mathbb{R}^3$.
- Initial position: $x \in \Omega$.
- Mean First Passage Time (MFPT): v(x).
- Domain boundary: $\partial \Omega = \partial \Omega_r$ (reflecting) $\cup \partial \Omega_a$ (absorbing).
- $\partial \Omega_a = \bigcup_{i=1}^N \partial \Omega_{\varepsilon_i}$: small absorbing traps (size $\sim \varepsilon$).

Continuum formulation



Figure 1: A Schematic of the Narrow Escape Problem in a 2-D and a 3-D domain.

Problem for the MFPT v = v(x) [Holcman, Schuss (2004)]:

$$\begin{cases} \bigtriangleup v = -\frac{1}{D}, & x \in \Omega, \\ v = 0, & x \in \partial \Omega_a; & \partial_n v = 0, & x \in \partial \Omega_r. \end{cases}$$

Average MFPT: $\bar{v} = \frac{1}{|\Omega|} \int_{\Omega} v(x) dx = \text{const.}$

The continuum model



Continuum problem for the MFPT:

$$\begin{cases} \bigtriangleup v = -\frac{1}{D}, & x \in \Omega, \\ v = 0, & x \in \partial \Omega_a = \bigcup_{j=1}^N \partial \Omega_{\varepsilon_j}, \\ \partial_n v = 0, & x \in \partial \Omega_r. \end{cases}$$

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Boundary value problem-based model:

Linear;

- Strongly heterogeneous Dirichlet/Neumann BCs;
- Singularly perturbed:

• $\varepsilon \to 0^+ \quad \Rightarrow \quad v \to +\infty \quad \text{a.e.}$

Some general results



Arbitrary 2D domain with smooth boundary; one trap [Holcman et al (2004, 2006)]

$$ar{v} \sim rac{|\Omega|}{\pi D} \left[-\logarepsilon + \mathcal{O}\left(1
ight)
ight]$$

Unit sphere; one trap [Singer et al (2006)]

$$ar{
u} \sim rac{|\Omega|}{4arepsilon D} \left[1 - rac{arepsilon}{\pi} \log arepsilon + \mathcal{O}\left(arepsilon
ight)
ight]$$

Arbitrary 3D domain with smooth boundary; one trap [Singer et al (2009)]

$$ar{\mathbf{v}} \sim rac{|\Omega|}{4arepsilon D} \left[1 - rac{arepsilon}{\pi} H \log arepsilon + \mathcal{O}\left(arepsilon
ight)
ight]$$

H: mean curvature at the center of the trap.

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Matched asymptotic expansions for:

• Sphere with *N* traps.

• Trap radii:
$$r_j = a_j \varepsilon$$
, $j = 1, ..., N$; capacitances: $c_j = 2a_j/\pi$.

MFPT and average MFPT [A.C., M.Ward, R.Straube (2010)]:

$$\begin{aligned} \mathbf{v}(x) &= \bar{\mathbf{v}} - \frac{|\Omega|}{DN\bar{c}} \sum_{j=1}^{N} c_j G_s(x; x_j) + \mathcal{O}(\varepsilon \log \varepsilon) \\ \bar{\mathbf{v}} &= \frac{|\Omega|}{2\pi\varepsilon DN\bar{c}} \left[1 + \varepsilon \log\left(\frac{2}{\varepsilon}\right) \frac{\sum_{j=1}^{N} c_j^2}{2N\bar{c}} + \frac{2\pi\varepsilon}{N\bar{c}} \mathbf{p}_c(x_1, \dots, x_N) - \frac{\varepsilon}{N\bar{c}} \sum_{j=1}^{N} c_j \kappa_j + \mathcal{O}(\varepsilon^2 \log \varepsilon) \right] \end{aligned}$$

- G_s(x; x_j): spherical Neumann Green's function (known);
- \bar{c} : average capacitance; $\kappa_j = \text{const}$;
- $p_c(x_1, \ldots, x_N)$: energy-like trap interaction term.

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N equal traps of radius ε :

• Average MFPT:

$$ar{
u} \sim rac{|\Omega|}{4arepsilon DN} \left[1 + rac{arepsilon}{\pi} \log\left(rac{2}{arepsilon}
ight) + rac{arepsilon}{\pi} \left(-rac{9N}{5} + 2(N-2)\log 2 + rac{3}{2} + rac{4}{N} \mathcal{H}(x_1, \dots, x_N)
ight)
ight] \, .$$

• Interaction energy:

$$\mathcal{H}(x_1,\ldots,x_N) = \sum_{i=1}^N \sum_{j=i+1}^N \left[\underbrace{\frac{1}{|x_i - x_j|}}_{Coulomb} - \underbrace{\frac{1}{2} \log |x_i - x_j|}_{Logarithmic} - \frac{1}{2} \log (2 + |x_i - x_j|) \right].$$

Optimal arrangements

- min $\overline{v} \Leftrightarrow \min \mathcal{H}(x_1, \ldots, x_N)$, a global optimization problem.
- "Thomson problem": optimal arrangements for the Coulomb potential.
- Optimal arrangements minimizing \bar{v} for $N \lesssim 100$: general software (e.g., LGO).

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Overview of some NE/NC/optimization work in the last years

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The Narrow Capture (NC) problem and the PDE model

Trapping reactions: whenever a diffusing particle hits a trap, it is immediately and permanently trapped.

- exciton trapping
- fluorescence quenching
- spin relaxation processes
- mean first-passage time: v(x)
- narrow capture: small trap size



$$\begin{array}{l} \Delta \nu(x) = -\frac{1}{D} , \quad x \in \Omega \backslash \Omega_{\mathfrak{a}}, \\ \partial_n \nu = 0 , \quad x \in \partial \Omega, \\ \nu = 0 , \quad x \in \partial \Omega_{\mathfrak{a}} = \cup_{j=1}^N \partial \Omega_{\varepsilon_j} \end{array}$$

$$\bar{v} = \frac{1}{|\Omega|} \int_{\Omega} v(x) \, d^n x$$



Unit sphere - exact and asymptotic solutions

• Exact solution when a single trap (radius= ε) is at the origin:

$$v_e(r) = \frac{1}{6D} \left[\frac{\varepsilon^3 + 2}{\varepsilon} - \frac{r^3 + 2}{r} \right], \quad \bar{v}_e = \frac{1}{6D} \left[\frac{\varepsilon^3 + 2}{\varepsilon} - \frac{18}{5} \right]$$

- Multiple traps: repel from each other and their own "reflections" in the boundary
- Asymptotic solutions: small, well-separated traps, far from the boundary; include an interaction term [A.C., M. Ward, 2011]

$$\begin{split} v_{A}(x) &= \frac{|\Omega|}{4\pi N \bar{c} D \varepsilon} \left[1 - 4\pi \varepsilon \sum_{j=1}^{N} c_{j} G(x; x_{j}) + \frac{4\pi \varepsilon}{N \bar{c}} p_{c}(\xi_{1}, ..., \xi_{N}) + \mathcal{O}(\varepsilon^{2}) \right] \\ \bar{v}_{A} &= \frac{|\Omega|}{4\pi N \bar{c} D \varepsilon} \left[1 + \frac{4\pi \varepsilon}{N \bar{c}} p_{c}(x_{1}, ..., x_{N}) + \mathcal{O}(\varepsilon^{2}) \right] \end{split}$$

 Expressed in terms of the Green's functions G(x, ξ) computed on trap pairs, and their regular parts R(ξ), and trap capacitances c_j.

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Exact and asymptotic solutions

- Capacitance depends on trap shape and size.
- Green's function:

$$\begin{split} \Gamma(x;\xi) &= G(x,\xi) = \frac{1}{4\pi |x-\xi|} + \frac{1}{4\pi |x| |x'-\xi|} \\ &+ \frac{1}{4\pi} \log \left(\frac{2}{1-|x| |\xi| \cos \theta + |x| |x'-\xi|} \right) + \frac{1}{8\pi} (|x|^2 + |\xi|^2) - \frac{7}{10\pi} \end{split}$$

• Every trap (ξ) interacts with other traps (x) and their images (x'): $xx' = r^2 = 1$.



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Exact and asymptotic solutions

- Capacitance depends on trap shape and size.
- Green's function:

$$\begin{split} \mathsf{F}(x;\xi) &= \mathsf{G}(x,\xi) = \frac{1}{4\pi |x-\xi|} + \frac{1}{4\pi |x| |x'-\xi|} \\ &+ \frac{1}{4\pi} \log \left(\frac{2}{1-|x| |\xi| \cos \theta + |x| |x'-\xi|} \right) + \frac{1}{8\pi} (|x|^2 + |\xi|^2) - \frac{7}{10\pi} \end{split}$$

- Every trap (ξ) interacts with other traps (x) and their images (x'): $xx' = r^2 = 1$.
- Green's function regular part:

$$\Gamma(\xi;\xi) = R(\xi) = \frac{1}{4\pi(1-|\xi|^2)} + \frac{1}{4\pi}\log\left(\frac{1}{1-|\xi|^2}\right) + \frac{|\xi|^2}{4\pi} - \frac{7}{10\pi}$$

• Trap interaction term:

$$p_c(\xi_1,...,\xi_N) = \sum_{i=1}^N \sum_{j=1}^N c_i c_j \Gamma(\xi_i,\xi_j)$$

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Some optimization results

- Asymptotic MFPT formulas tested vs. exact/numerical: work far beyond limits [*J. Gilbert and A.C., 2019*].
- Putative locally optimal configurations for $1 \le N \le 100$ computed.
- Traps often lie close to spherical shells.
- There may or may not be a trap at the center.
- Example: N = 24





Image: A match the second s

Global optimization: traps (approximately) on shells



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Projects and collaborators

• with Michael Ward and R. Straube (2010):

Asymptotic mean first passage time (MFPT), NE, sphere with small surface traps

• with Michael Ward (2010):

Asymptotic MFPT, NC, sphere with small interior traps

- with Ashton Reimer and Michael Ward (2012): NE asymptotic vs. numerical MFPT; applicability limits of asymptotic solutions
- with Daniel Zawada (2013):

NE, unit sphere: homogenization limit and optimal arrangements of $N \gg 1$ traps, the N^2 conjecture

• with Daniel Gomez (2015):

NE, nonspherical 3D domains, effects of boundary curvature

• with Wesley Ridgway (2018, 2019):

Locally and globally optimal arrangements of particles repelling on the unit sphere surface. Results for NE and NC problems

• with Jason Gilbert (2019, ongoing):

Globally optimal trap arrangements for NC in unit sphere. Optimal NC trap configurations in an ellipse

• with Vaibhava Srivastava (finishing up):

Full Brownian simulations for NE in a sphere; comparison with PDE MFPT/asymptotic results; study of boundary effects & anisotropic diffusion

Thanks everyone for listening!.. and...



Image: A math a math