

# Conservation Laws of Models of Biological Membranes in the Framework of Nonlinear Elastodynamics

Alexei Cheviakov, J.-F. Ganghoffer

University of Saskatchewan, Canada / Université de Lorraine, France

EUROMECH Colloquium 560

February 10, 2015

- 1 Local Conservation Laws
- 2 Fiber-Reinforced Materials; Governing Equations
- 3 Single Fiber Family, Ansatz 1 – One-Dimensional Shear Waves
- 4 Single Fiber Family, Ansatz 2 – 2D Shear Waves
- 5 Two Fiber Families, Planar Case
- 6 A Viscoelastic Model, Single Fiber Family, 1D Shear Waves
- 7 Discussion

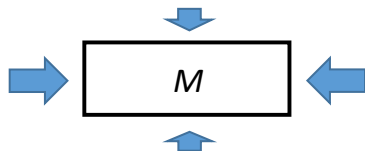
- 1 Local Conservation Laws
- 2 Fiber-Reinforced Materials; Governing Equations
- 3 Single Fiber Family, Ansatz 1 – One-Dimensional Shear Waves
- 4 Single Fiber Family, Ansatz 2 – 2D Shear Waves
- 5 Two Fiber Families, Planar Case
- 6 A Viscoelastic Model, Single Fiber Family, 1D Shear Waves
- 7 Discussion

## Motivation

- Interesting mathematics!
- Study of **fundamental properties** of nonlinear elastodynamics equations arising in applications.

## Notation

- $D_t = \frac{\partial u}{\partial t} \equiv u_t.$

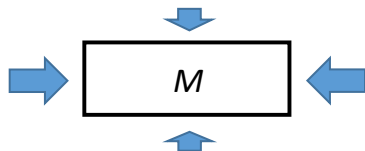


## Global form

- Global quantity  $M \in \mathcal{D}$  changes **only due to boundary fluxes**.

$$M = \int_{\mathcal{D}} \Theta \, dV; \quad \frac{d}{dt} M = \oint_{\partial \mathcal{D}} \Psi \cdot d\mathbf{S}.$$

- $\Theta[\mathbf{u}]$ : conserved density;  $\Psi$ : flux vector.



## Global form

- Global quantity  $M \in \mathcal{D}$  changes **only due to boundary fluxes**.

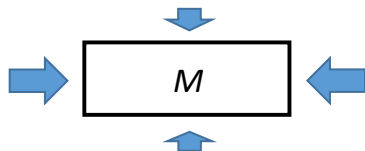
$$M = \int_{\mathcal{D}} \Theta \, dV; \quad \frac{d}{dt} M = \oint_{\partial \mathcal{D}} \Psi \cdot d\mathbf{S}.$$

- $\Theta[\mathbf{u}]$ : conserved density;  $\Psi$ : flux vector.

## Local form

- **A local conservation law**: a divergence expression equal to zero, e.g.,

$$D_t \Theta[\mathbf{u}] + D_i \Psi^i[\mathbf{u}] = 0.$$



## Global form

- Global quantity  $M \in \mathcal{D}$  changes **only due to boundary fluxes**.

$$M = \int_{\mathcal{D}} \Theta \, dV; \quad \frac{d}{dt} M = \oint_{\partial \mathcal{D}} \Psi \cdot d\mathbf{S}.$$

- $\Theta[\mathbf{u}]$ : conserved density;  $\Psi$ : flux vector.

## Global conserved quantity:

$$\frac{d}{dt} M = D_t \int_V \Theta \, dV = 0 \quad \text{when} \quad \oint_{\partial V} \Psi \cdot d\mathbf{S} = 0.$$

## ODEs

- Constants of motion.
- Integration.

## PDEs

- Rates of change of physical variables; constants of motion.
- Differential constraints.
- Analysis: existence, uniqueness, stability, integrability, linearization.
- Potentials, stream functions, etc.
- Conserved forms for numerical methods (finite volume, etc.).
- Numerical method testing.



For equations following from a **variational principle**:

- Can use **Noether's theorem**.
- Conservation laws are connected with variational symmetries.
- Technically difficult.

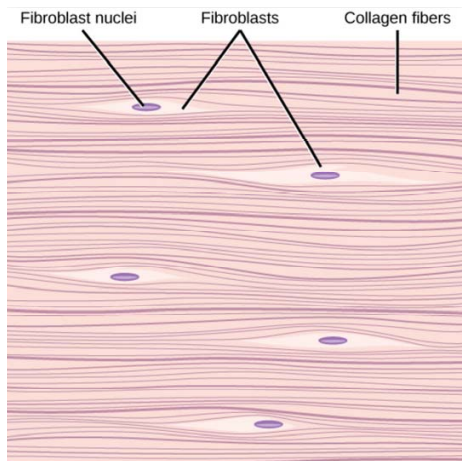
For equations following from a **variational principle**:

- Can use **Noether's theorem**.
- Conservation laws are connected with variational symmetries.
- Technically difficult.

For **generic models**: Direct conservation law construction method

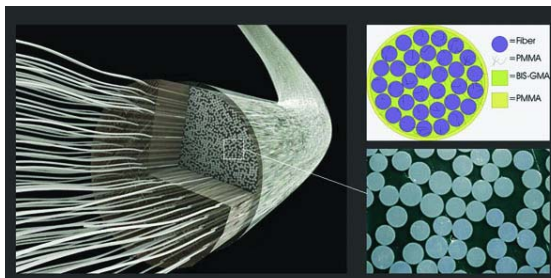
- Conservation laws can be sought in the **characteristic form**  $\Lambda_\sigma R^\sigma \equiv D_i \Phi^i$ .
- **Systematically** find the multipliers  $\Lambda_\sigma$ .
- Direct method is **complete** for a wide class of systems.
- Implemented in Maple/GeM: **symbolic computations**.

- 1 Local Conservation Laws
- 2 Fiber-Reinforced Materials; Governing Equations**
- 3 Single Fiber Family, Ansatz 1 – One-Dimensional Shear Waves
- 4 Single Fiber Family, Ansatz 2 – 2D Shear Waves
- 5 Two Fiber Families, Planar Case
- 6 A Viscoelastic Model, Single Fiber Family, 1D Shear Waves
- 7 Discussion



Collagen fiber in tendons.

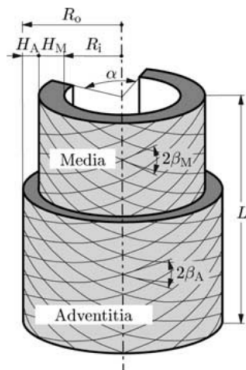
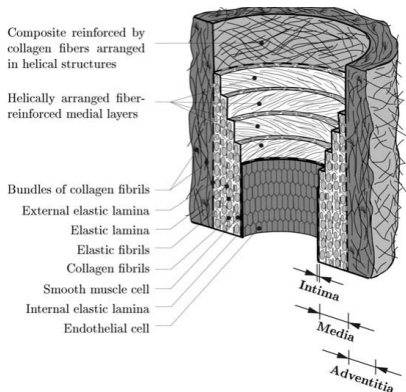
Single fiber family.



A fiber-reinforced composite in dentistry.

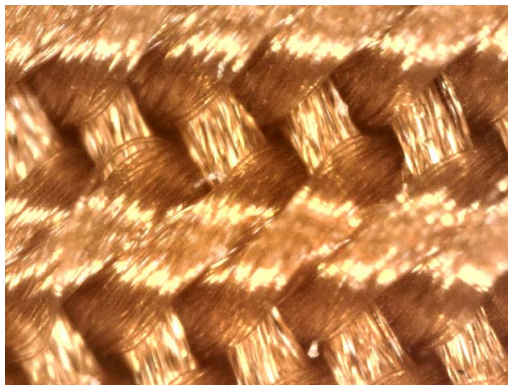
Single fiber family.

# Examples



Arterial tissue (Holzapfel, Gasser, and Ogden, 2000).

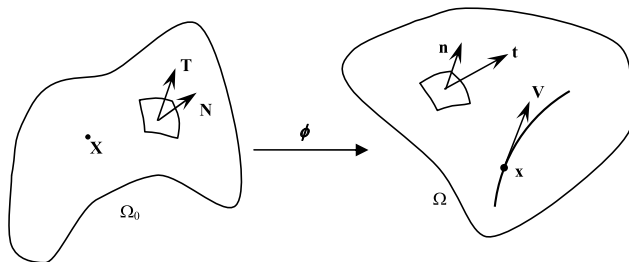
Two helically arranged fiber families.



Fabric – two fiber families.

- **Appropriate framework:** incompressible hyperelasticity / viscoelasticity.





**Fig. 1.** Material and Eulerian coordinates.

## Material picture

- Material points  $\mathbf{X} \in \Omega_0$ .
- **Actual position** of a material point:  $\mathbf{x} = \phi(\mathbf{X}, t) \in \Omega$ .

- Deformation gradient:  $\mathbf{F}(\mathbf{X}, t) = \nabla \phi$ ,  $F_j^i = \frac{\partial x^i}{\partial X^j}$ .

## Incompressibility:

$$J = \det \mathbf{F} = \left| \frac{\partial x^i}{\partial X^j} \right| = 1, \quad \rho = \rho_0 / J = \rho_0(\mathbf{X}).$$

## Incompressibility:

$$J = \det \mathbf{F} = \left| \frac{\partial x^i}{\partial X^j} \right| = 1, \quad \rho = \rho_0 / J = \rho_0(\mathbf{X}).$$

## Equations of motion:

$$\rho_0 \mathbf{x}_{tt} = \operatorname{div}_{(X)} \mathbf{P} + \rho_0 \mathbf{R}, \quad J = 1.$$

- $\mathbf{R} = \mathbf{R}(\mathbf{X}, t)$ : total body force per unit mass;  $\rho_0(\mathbf{X})$ : density.
- Use  $\mathbf{R} = 0$ ,  $\rho_0 = \text{const.}$

## Stress tensor (incompressible):

$$P^{ij} = -p (F^{-1})^{ij} + \rho_0 \frac{\partial W}{\partial F_{ij}}, \quad (1)$$

- $W$ : scalar **strain energy density**;  $p$ : **hydrostatic pressure**.

## Strain Energy Density

$$W = W_{iso} + W_{aniso}.$$

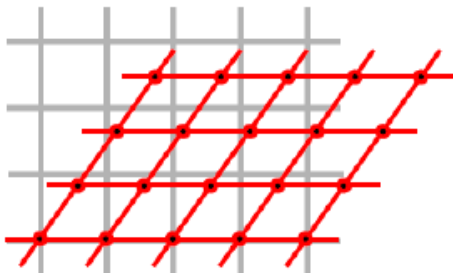
## Isotropic Strain Energy Density

- **Right Cauchy-Green strain tensor**:  $\mathbf{C} = \mathbf{F}^T \mathbf{F}$ ,

$$I_1 = \text{Tr } \mathbf{C}, \quad I_2 = \frac{1}{2}[(\text{Tr } \mathbf{C})^2 - \text{Tr}(\mathbf{C}^2)]. \quad (2)$$

- **Mooney-Rivlin materials**:

$$W_{iso} = a(I_1 - 3) + b(I_2 - 3), \quad a, b > 0.$$



## Fiber directions

- **Reference configuration:** fibers along  $\mathbf{A}$  ( $|\mathbf{A}| = 1$ ).
- **Actual configuration:** fibers along  $\mathbf{a}$  ( $|\mathbf{a}| = 1$ ).
- **Fiber stretch factor:**

$$\lambda \mathbf{a} = \mathbf{F} \mathbf{A} \quad \Rightarrow \quad \lambda^2 = \mathbf{A}^T \mathbf{C} \mathbf{A}.$$

## Anisotropic Strain Energy Density

- Fiber invariants:

$$I_4 = \mathbf{A}^T \mathbf{C} \mathbf{A}, \quad I_5 = \mathbf{A}^T \mathbf{C}^2 \mathbf{A}.$$

- General constitutive model:

$$W_{aniso} = f(I_4 - 1, I_5 - 1), \quad f(0, 0) = 0.$$

- **Standard reinforcement model:**  $W_{aniso} = q(I_4 - 1)^2$ .

## Anisotropic Strain Energy Density

- Fiber invariants:

$$I_4 = \mathbf{A}^T \mathbf{C} \mathbf{A}, \quad I_5 = \mathbf{A}^T \mathbf{C}^2 \mathbf{A}.$$

- General constitutive model:

$$W_{aniso} = f(I_4 - 1, I_5 - 1), \quad f(0, 0) = 0.$$

- Standard reinforcement model:  $W_{aniso} = q(I_4 - 1)^2$ .

## Equations of motion:

$$\rho_0 \mathbf{x}_{tt} = \operatorname{div}_{(X)} \mathbf{P}, \quad J = \det \left[ \frac{\partial x^i}{\partial X^j} \right] = 1,$$

$$P^{ij} = -p (F^{-1})^{ji} + \rho_0 \frac{\partial W}{\partial F_{ij}}.$$

- Strain energy density, single fiber family:

$$W = W_{iso} + W_{aniso} = a(I_1 - 3) + b(I_2 - 3) + q(I_4 - 1)^2; \quad a, b, q > 0.$$

- 1 Local Conservation Laws
- 2 Fiber-Reinforced Materials; Governing Equations
- 3 Single Fiber Family, Ansatz 1 – One-Dimensional Shear Waves**
- 4 Single Fiber Family, Ansatz 2 – 2D Shear Waves
- 5 Two Fiber Families, Planar Case
- 6 A Viscoelastic Model, Single Fiber Family, 1D Shear Waves
- 7 Discussion



## Equilibrium and Displacements

- Equilibrium/no displacement:  $\mathbf{x} = \mathbf{X}$ , *natural state*.
- Time-dependent, with displacement:  $\mathbf{x} = \mathbf{X} + \mathbf{G}$ ,  $\mathbf{G} = \mathbf{G}(\mathbf{X}, t)$ .
- No linearization, or assumption of smallness of  $\mathbf{G}$ , etc.

## Equilibrium and Displacements

- Equilibrium/no displacement:  $\mathbf{x} = \mathbf{X}$ , *natural state*.
- Time-dependent, with displacement:  $\mathbf{x} = \mathbf{X} + \mathbf{G}$ ,  $\mathbf{G} = \mathbf{G}(\mathbf{X}, t)$ .
- No linearization, or assumption of smallness of  $\mathbf{G}$ , etc.

## Motions Transverse to a Plane

$$\mathbf{x} = \begin{bmatrix} X^1 \\ X^2 \\ X^3 + G(X^1, t) \end{bmatrix}, \quad \mathbf{A} = \begin{bmatrix} \cos \gamma \\ 0 \\ \sin \gamma \end{bmatrix}.$$

## Equilibrium and Displacements

- Equilibrium/no displacement:  $\mathbf{x} = \mathbf{X}$ , *natural state*.
- Time-dependent, with displacement:  $\mathbf{x} = \mathbf{X} + \mathbf{G}$ ,  $\mathbf{G} = \mathbf{G}(\mathbf{X}, t)$ .
- No linearization, or assumption of smallness of  $\mathbf{G}$ , etc.

## Motions Transverse to a Plane

$$\mathbf{x} = \begin{bmatrix} X^1 \\ X^2 \\ X^3 + \mathbf{G}(X^1, t) \end{bmatrix}, \quad \mathbf{A} = \begin{bmatrix} \cos \gamma \\ 0 \\ \sin \gamma \end{bmatrix}.$$

## Deformation gradient:

$$\mathbf{F} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ \partial \mathbf{G} / \partial X_1 & 0 & 1 \end{bmatrix}, \quad J = |\mathbf{F}| \equiv 1.$$

## Equation of motion for one-dimensional displacements:

- Denote

$$X^1 = x, \quad G = G(x, t), \quad \alpha = 2(a + b) > 0, \quad \beta = 4q > 0.$$

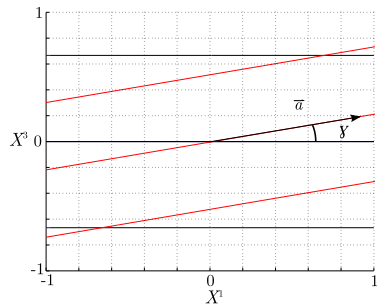
- Single nonlinear PDE:

$$G_{tt} = (\alpha + \beta \cos^2 \gamma (3 \cos^2 \gamma (G_x)^2 + 6 \sin \gamma \cos \gamma G_x + 2 \sin^2 \gamma)) G_{xx}.$$

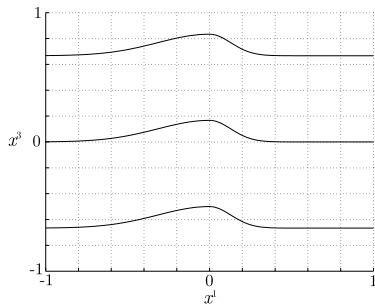
- Pressure is found explicitly:

$$p = \beta \rho_0 \cos^3 \gamma (\cos \gamma G_x + 2 \sin \gamma) G_x + f(t).$$

# One-Dimensional Shear Waves



Reference Configuration



Actual Configuration

## 1D wave model in the case of a single fiber family

- Wave equation:

$$G_{tt} = \left( \alpha + \beta \cos^2 \gamma \left( 3 \cos^2 \gamma (G_x)^2 + 6 \sin \gamma \cos \gamma G_x + 2 \sin^2 \gamma \right) \right) G_{xx}.$$

- General PDE class:

$$G_{tt} = (A(G_x)^2 + BG_x + C) G_{xx},$$

$$A = 3\beta \cos^4 \gamma > 0,$$

$$B = 6\beta \sin \gamma \cos^3 \gamma, \quad 0 \leq \gamma < \pi/2.$$

$$C = \alpha + \frac{1}{2}\beta \sin^2(2\gamma) > 0,$$

## 1D wave model in the case of a single fiber family

- Wave equation:

$$G_{tt} = \left( \alpha + \beta \cos^2 \gamma \left( 3 \cos^2 \gamma (G_x)^2 + 6 \sin \gamma \cos \gamma G_x + 2 \sin^2 \gamma \right) \right) G_{xx}.$$

- General PDE class:  $G_{tt} = (A(G_x)^2 + BG_x + C) G_{xx},$

$$A = 3\beta \cos^4 \gamma > 0,$$

$$B = 6\beta \sin \gamma \cos^3 \gamma, \quad 0 \leq \gamma < \pi/2.$$

$$C = \alpha + \frac{1}{2}\beta \sin^2(2\gamma) > 0,$$

## Loss of hyperbolicity

- May occur when  $B^2 - 4AC \geq 0$ , i.e.,  $\sin^2(2\gamma) \geq \frac{4\alpha}{\beta}$ .
- Can only happen for “strong” fiber contribution:  $\beta \geq \frac{4\alpha}{\sin^2(2\gamma)}$ .

## 1D wave model in the case of a single fiber family

- Wave equation:

$$G_{tt} = \left( \alpha + \beta \cos^2 \gamma \left( 3 \cos^2 \gamma (G_x)^2 + 6 \sin \gamma \cos \gamma G_x + 2 \sin^2 \gamma \right) \right) G_{xx}.$$

- General PDE class:  $G_{tt} = (A(G_x)^2 + BG_x + C) G_{xx},$

$$A = 3\beta \cos^4 \gamma > 0,$$

$$B = 6\beta \sin \gamma \cos^3 \gamma, \quad 0 \leq \gamma < \pi/2.$$

$$C = \alpha + \frac{1}{2}\beta \sin^2(2\gamma) > 0,$$

## Variational structure

- Any nonlinear PDE of the above class follows from a **variational principle**, with the Lagrangian density (*up to equivalence*)

$$\mathcal{L} = \frac{1}{2} G_t^2 + \frac{A}{4} G G_x^2 G_{xx} + \frac{B}{3} G G_x G_{xx} - \frac{C}{2} G_x^2.$$



## 1D wave model in the case of a single fiber family

- Wave equation:

$$G_{tt} = \left( \alpha + \beta \cos^2 \gamma \left( 3 \cos^2 \gamma (G_x)^2 + 6 \sin \gamma \cos \gamma G_x + 2 \sin^2 \gamma \right) \right) G_{xx}.$$

- General PDE class:  $G_{tt} = (A(G_x)^2 + BG_x + C) G_{xx},$

$$A = 3\beta \cos^4 \gamma > 0,$$

$$B = 6\beta \sin \gamma \cos^3 \gamma, \quad 0 \leq \gamma < \pi/2.$$

$$C = \alpha + \frac{1}{2}\beta \sin^2(2\gamma) > 0,$$

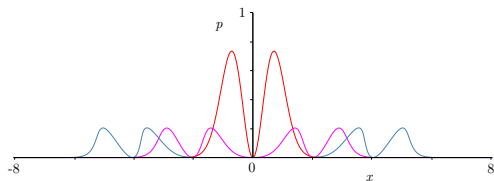
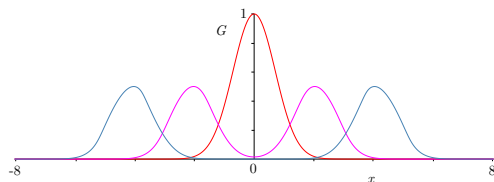
## Simplification

- Depending on the sign of  $B^2 - 4AC$ , equation can be transformed to

$$u_{tt} = \left( (u_x)^2 + K \right) u_{xx}, \quad K = 0, \pm 1.$$

# One-Dimensional Shear Waves

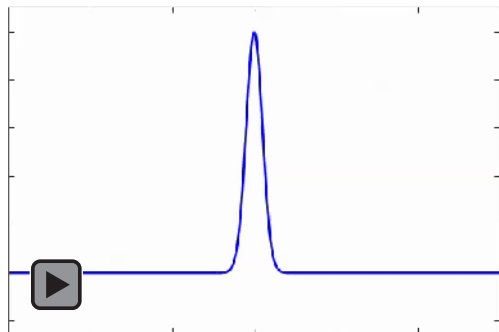
A numerical solution



- Wave speed dependent on  $u_x$ .
- Numerical instabilities.
- **Wave breaking**, applicability?

# One-Dimensional Shear Waves

A numerical solution



## Find local CLs for the nonlinear wave equation

- Model:  $u_{tt} = (u_x^2 + 1) u_{xx}$ .
- Conserved form:  $\Lambda[u] (u_{tt} - (u_x^2 + 1) u_{xx}) = D_t \Theta + D_x \Psi = 0$ .
- Basic CLs:

## Find local CLs for the nonlinear wave equation

- Model:  $u_{tt} = (u_x^2 + 1) u_{xx}$ .
- Conserved form:  $\Lambda[u] (u_{tt} - (u_x^2 + 1) u_{xx}) = D_t \Theta + D_x \Psi = 0$ .
- Basic CLs:

### Eulerian momentum:

- $\Lambda = 1$ ,

$$D_t(u_t) - D_x \left[ u_x \left( \frac{1}{3} u_x^2 + 1 \right) \right] = 0.$$

### Lagrangian momentum:

- $\Lambda = u_x$ ,

$$D_t(u_x u_t) - D_x \left( \frac{1}{2} (u_t^2 + u_x^2) + \frac{1}{4} u_x^4 \right) = 0.$$

## Find local CLs for the nonlinear wave equation

- Model:  $u_{tt} = (u_x^2 + 1) u_{xx}$ .
- Conserved form:  $\Lambda[u] (u_{tt} - (u_x^2 + 1) u_{xx}) = D_t \Theta + D_x \Psi = 0$ .
- Basic CLs:

## Energy:

- $\Lambda = u_t$ ,

$$D_t \left( \frac{1}{2} u_t^2 + \frac{1}{2} u_x^2 + \frac{1}{12} u_x^4 \right) - D_x \left[ u_t u_x \left( \frac{1}{3} u_x^2 + 1 \right) \right] = 0.$$

## Center of mass theorem:

- $\Lambda = t$ ,

$$D_t (t u_t - u) - D_x \left[ t u_x \left( \frac{1}{3} u_x^2 + 1 \right) \right] = 0.$$

## Find local CLs for the nonlinear wave equation

- Model:  $u_{tt} = (u_x^2 + 1) u_{xx}$ .
- Conserved form:  $\Lambda[u] (u_{tt} - (u_x^2 + 1) u_{xx}) = D_t \Theta + D_x \Psi = 0$ .

## Find local CLs for the nonlinear wave equation

- Model:  $u_{tt} = (u_x^2 + 1) u_{xx}$ .
- Conserved form:  $\Lambda[u] (u_{tt} - (u_x^2 + 1) u_{xx}) = D_t \Theta + D_x \Psi = 0$ .

## An infinite family of conservation laws

- Multiplier: any function  $\Lambda(u_t, u_x)$  satisfying

$$\Lambda_{u_x, u_x} = (u_x^2 + 1) \Lambda_{u_t, u_t}.$$

## Linearization by a Legendre contact transformation:

$$y = u_x, \quad z = u_t, \quad w(y, z) = u(x, t) - xu_x - tu_t;$$
$$w_{yy} = (y^2 + 1) w_{zz}.$$



## Find local CLs for the nonlinear wave equation

- Model:  $u_{tt} = (u_x^2 + 1) u_{xx}$ .
- Conserved form:  $\Lambda[u] (u_{tt} - (u_x^2 + 1) u_{xx}) = D_t \Theta + D_x \Psi = 0$ .

## A more exotic, 2nd-order CL:

- For  $\Lambda$  depending on 3rd derivatives, can have, e.g.,

$$D_t \frac{u_{xx}}{u_{tx} - (u_x^2 + 1)u_{xx}} + D_x \frac{u_{tx}}{u_{tx}^2 - (u_x^2 + 1)u_{xx}^2} = 0.$$

- 1 Local Conservation Laws
- 2 Fiber-Reinforced Materials; Governing Equations
- 3 Single Fiber Family, Ansatz 1 – One-Dimensional Shear Waves
- 4 Single Fiber Family, Ansatz 2 – 2D Shear Waves**
- 5 Two Fiber Families, Planar Case
- 6 A Viscoelastic Model, Single Fiber Family, 1D Shear Waves
- 7 Discussion

### Displacements transverse to an axis:

$$\mathbf{X} = \begin{bmatrix} X^1 \\ X^2 + H(X^1, t) \\ X^3 + G(X^1, t) \end{bmatrix}, \quad \mathbf{A} = \begin{bmatrix} \cos \gamma \\ 0 \\ \sin \gamma \end{bmatrix}.$$

Displacements transverse to an axis:

$$\mathbf{X} = \begin{bmatrix} X^1 \\ X^2 + H(X^1, t) \\ X^3 + G(X^1, t) \end{bmatrix}, \quad \mathbf{A} = \begin{bmatrix} \cos \gamma \\ 0 \\ \sin \gamma \end{bmatrix}.$$

Deformation gradient:

$$\mathbf{F} = \begin{bmatrix} 1 & 0 & 0 \\ \partial H / \partial X_1 & 1 & 0 \\ \partial G / \partial X_1 & 0 & 1 \end{bmatrix}, \quad J = |\mathbf{F}| \equiv 1.$$

### Displacements transverse to an axis:

$$\mathbf{X} = \begin{bmatrix} X^1 \\ X^2 + H(X^1, t) \\ X^3 + G(X^1, t) \end{bmatrix}, \quad \mathbf{A} = \begin{bmatrix} \cos \gamma \\ 0 \\ \sin \gamma \end{bmatrix}.$$

### Deformation gradient:

$$\mathbf{F} = \begin{bmatrix} 1 & 0 & 0 \\ \partial H / \partial X_1 & 1 & 0 \\ \partial G / \partial X_1 & 0 & 1 \end{bmatrix}, \quad J = |\mathbf{F}| \equiv 1.$$

### Governing PDEs:

- Denote  $X^1 = x$ ,  $G = G(x, t)$ ,  $H = H(x, t)$ .

## Displacements transverse to an axis:

$$\mathbf{X} = \begin{bmatrix} X^1 \\ X^2 + H(X^1, t) \\ X^3 + G(X^1, t) \end{bmatrix}, \quad \mathbf{A} = \begin{bmatrix} \cos \gamma \\ 0 \\ \sin \gamma \end{bmatrix}.$$

## Coupled nonlinear wave equations:

$$0 = p_x - 2\beta\rho_0 \cos^3 \gamma [(\cos \gamma G_x + \sin \gamma) G_{xx} + \cos \gamma H_x H_{xx}],$$

$$H_{tt} = \alpha H_{xx} + \beta \cos^3 \gamma \left[ \cos \gamma ([G_x^2 + H_x^2] H_{xx} + 2G_x H_x G_{xx}) + 2 \sin \gamma \frac{\partial}{\partial X} (G_x H_x) \right],$$

$$G_{tt} = \alpha G_{xx} + \beta \cos^2 \gamma [2 \sin^2 \gamma G_{xx} + \cos^2 \gamma (2G_x H_x H_{xx} + (H_x^2 + 3G_x^2) G_{xx}) \\ + \sin 2\gamma (3G_x G_{xx} + H_x H_{xx})].$$

## Displacements transverse to an axis:

$$\mathbf{X} = \begin{bmatrix} X^1 \\ X^2 + H(X^1, t) \\ X^3 + G(X^1, t) \end{bmatrix}, \quad \mathbf{A} = \begin{bmatrix} \cos \gamma \\ 0 \\ \sin \gamma \end{bmatrix}.$$

## Coupled nonlinear wave equations:

$$0 = p_x - 2\beta\rho_0 \cos^3 \gamma [(\cos \gamma G_x + \sin \gamma) G_{xx} + \cos \gamma H_x H_{xx}],$$

$$H_{tt} = \alpha H_{xx} + \beta \cos^3 \gamma \left[ \cos \gamma ([G_x^2 + H_x^2] H_{xx} + 2G_x H_x G_{xx}) + 2 \sin \gamma \frac{\partial}{\partial X} (G_x H_x) \right],$$

$$G_{tt} = \alpha G_{xx} + \beta \cos^2 \gamma [2 \sin^2 \gamma G_{xx} + \cos^2 \gamma (2G_x H_x H_{xx} + (H_x^2 + 3G_x^2) G_{xx}) \\ + \sin 2\gamma (3G_x G_{xx} + H_x H_{xx})].$$

## Subcase 1: $\gamma = \pi/2$

$$H_{tt} = \alpha H_{xx}, \quad G_{tt} = \alpha G_{xx}.$$

Subcase 2:  $\gamma = 0$

$$H_{tt} = \alpha H_{xx} + \beta \left[ \left( 3H_x^2 + G_x^2 \right) H_{xx} + 2G_x H_x G_{xx} \right],$$

$$G_{tt} = \alpha G_{xx} + \beta \left[ \left( 2G_x H_x H_{xx} + \left( H_x^2 + 3G_x^2 \right) G_{xx} \right) \right].$$

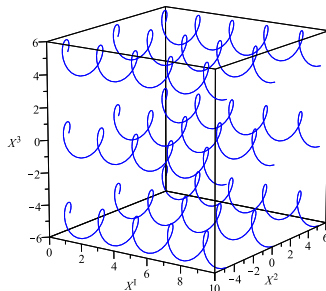
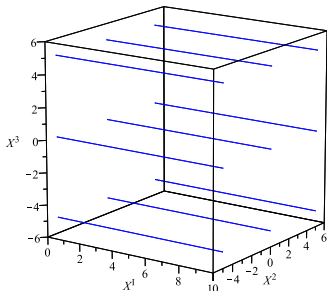


## Subcase 2: $\gamma = 0$

$$H_{tt} = \alpha H_{xx} + \beta \left( [3H_x^2 + G_x^2] H_{xx} + 2G_x H_x G_{xx} \right),$$

$$G_{tt} = \alpha G_{xx} + \beta \left( 2G_x H_x H_{xx} + (H_x^2 + 3G_x^2) G_{xx} \right).$$

- Exact **traveling wave solutions** can be derived [A.C., J.-F.G., S.St.Jean (2015)].
- e.g. Carroll-type nonlinear rotational shear waves



## Compute local CLs for the coupled model

$$H_{tt} = \alpha H_{xx} + \beta \left[ \left( \left[ 3H_x^2 + G_x^2 \right] H_{xx} + 2G_x H_x G_{xx} \right) \right],$$

$$G_{tt} = \alpha G_{xx} + \beta \left[ \left( 2G_x H_x H_{xx} + \left( H_x^2 + 3G_x^2 \right) G_{xx} \right) \right].$$

## Compute local CLs for the coupled model

$$H_{tt} = \alpha H_{xx} + \beta \left[ \left( 3H_x^2 + G_x^2 \right) H_{xx} + 2G_x H_x G_{xx} \right],$$

$$G_{tt} = \alpha G_{xx} + \beta \left[ \left( 2G_x H_x H_{xx} + \left( H_x^2 + 3G_x^2 \right) G_{xx} \right) \right].$$

## Linear momenta:

$$\Theta_1 = H_t, \quad \Theta_2 = G_t,$$

## x-components of the Lagrangian and the Angular momentum:

$$\Theta_3 = G_x G_t + G_x G_t, \quad \Theta_4 = -GH_t + HG_t,$$

## Compute local CLs for the coupled model

$$H_{tt} = \alpha H_{xx} + \beta \left[ \left( 3H_x^2 + G_x^2 \right) H_{xx} + 2G_x H_x G_{xx} \right],$$

$$G_{tt} = \alpha G_{xx} + \beta \left[ \left( 2G_x H_x H_{xx} + \left( H_x^2 + 3G_x^2 \right) G_{xx} \right) \right].$$

## Energy:

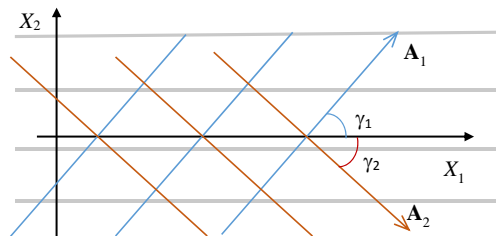
$$\Theta_5 = \frac{1}{2}(G_t^2 + H_t^2) + \frac{\alpha}{2}(G_x^2 + H_x^2) + \frac{\beta}{4}(G_x^2 + H_x^2)^2.$$

## Center of mass theorem:

$$\Theta_6 = tG_t - G, \quad \Theta_7 = tH_t - H.$$

- 1 Local Conservation Laws
- 2 Fiber-Reinforced Materials; Governing Equations
- 3 Single Fiber Family, Ansatz 1 – One-Dimensional Shear Waves
- 4 Single Fiber Family, Ansatz 2 – 2D Shear Waves
- 5 Two Fiber Families, Planar Case**
- 6 A Viscoelastic Model, Single Fiber Family, 1D Shear Waves
- 7 Discussion

# A Two-Fiber Planar Model



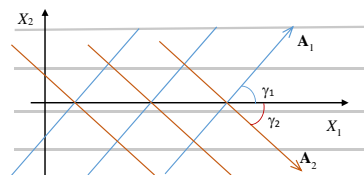
Fiber invariants:

$$l_4 = \lambda_1^2 = \mathbf{A}_1^T \mathbf{C} \mathbf{A}_1, \quad l_6 = \lambda_2^2 = \mathbf{A}_2^T \mathbf{C} \mathbf{A}_2, \quad l_8 = (\mathbf{A}_1^T \mathbf{A}_2)(\mathbf{A}_1^T \mathbf{C} \mathbf{A}_2).$$

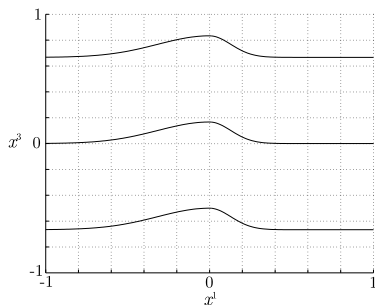
Strain energy density:

$$W = a(l_1 - 3) + b(l_2 - 3) + q_1(l_4 - 1)^2 + q_2(l_6 - 1)^2 + K_1 l_8^2 + K_2 l_8.$$

# One-Dimensional Shear Waves



Reference Configuration



Actual Configuration

Displacements transverse to an axis:

$$\mathbf{X} = \begin{bmatrix} X^1 \\ X^2 + G(X^1, t) \end{bmatrix}, \quad \rho = \rho(X^1, t).$$



## Displacements transverse to an axis:

$$\mathbf{X} = \begin{bmatrix} X^1 \\ X^2 + G(X^1, t) \end{bmatrix}, \quad \rho = \rho(X^1, t).$$

## Equations:

- Denote  $X^1 = x$ .
- Incompressibility condition is again identically satisfied.
- $\rho(x, t)$  found explicitly.
- Displacement  $G(x, t)$  satisfies a PDE from **the same general class**

$$G_{tt} = (A(G_x)^2 + BG_x + C) G_{xx},$$

where

$$A = A(K_1, q_{1,2}, \gamma_{1,2}), \quad B = B(K_1, q_{1,2}, \gamma_{1,2}), \quad C = C(K_{1,2}, q_{1,2}, \gamma_{1,2}),$$

## Nonlinear wave equation

$$G_{tt} = (A(G_x)^2 + BG_x + C) G_{xx},$$

- Same **conservation laws** as found before!

## Nonlinear wave equation

$$G_{tt} = (A(G_x)^2 + BG_x + C) G_{xx},$$

- Same **conservation laws** as found before!

## Variational structure

- Any nonlinear PDE of the above class follows from a **variational principle**, with the Lagrangian density (*up to equivalence*)

$$\mathcal{L} = \frac{1}{2} G_t^2 + \frac{A}{4} G G_x^2 G_{xx} + \frac{B}{3} G G_x G_{xx} - \frac{C}{2} G_x^2$$

## Nonlinear wave equation

$$G_{tt} = (A(G_x)^2 + BG_x + C) G_{xx},$$

- Same **conservation laws** as found before!

## Simplification

- Depending on the sign of  $B^2 - 4AC$ , PDE can be transformed to

$$u_{tt} = \left( (u_x)^2 \pm K \right) u_{xx}, \quad K = 0, \pm 1.$$

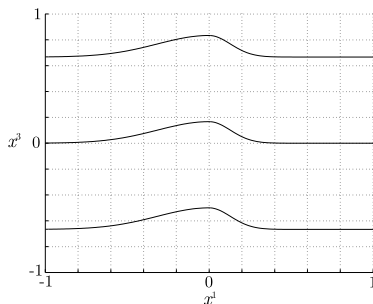
- 1 Local Conservation Laws
- 2 Fiber-Reinforced Materials; Governing Equations
- 3 Single Fiber Family, Ansatz 1 – One-Dimensional Shear Waves
- 4 Single Fiber Family, Ansatz 2 – 2D Shear Waves
- 5 Two Fiber Families, Planar Case
- 6 A Viscoelastic Model, Single Fiber Family, 1D Shear Waves**
- 7 Discussion

A hyper-viscoelastic model:

- An extra “invariant”:  $J_2 = \text{Tr}(\dot{\mathbf{C}}^2)$ .

Total potential, one fiber family:

$$W = a(I_1 - 3) + b(I_2 - 3) + q_1 (I_4 - 1)^2 + \frac{\eta}{4} J_2 (I_1 - 3).$$



## Equation of motion:

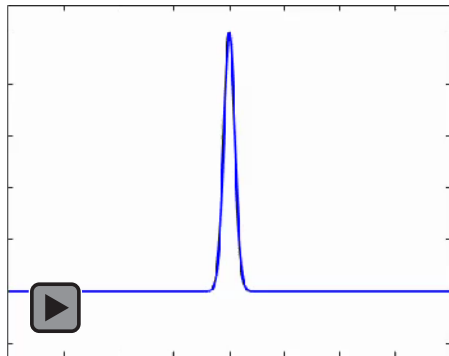
- Case: shear wave propagating along the fibers,  $X^1$ .
- Single nonlinear PDE:

$$G_{tt} = (\alpha + 3\beta G_x^2)G_{xx} + \eta [2(1 + 4G_x^2)G_x G_{tx} G_{xx} + (1 + 2G_x^2)G_x^2 G_{txx}].$$

- D'Alembert-type example: no wave breaking...

# One-Dimensional Shear Waves

A numerical solution





## Compute local CLs for the coupled model

$$G_{tt} = (\alpha + 3\beta G_x^2) G_{xx} + \eta [2(1 + 4G_x^2) G_x G_{tx} G_{xx} + (1 + 2G_x^2) G_x^2 G_{txx}].$$

- $\alpha = \eta = 1$ .

## Compute local CLs for the coupled model

$$G_{tt} = (\alpha + 3\beta G_x^2) G_{xx} + \eta [2(1 + 4G_x^2) G_x G_{tx} G_{xx} + (1 + 2G_x^2) G_x^2 G_{txx}].$$

- $\alpha = \eta = 1.$

## CL 1:

$$D_t(u_t - (1 + 2u_x^2)u_x^2 u_{xx}) - D_x((1 + \beta u_x^2)u_x) = 0.$$

## Potential system:

$$v_x = u_t - (1 + 2u_x^2)u_x^2 u_{xx}, \quad v_t = (1 + \beta u_x^2)u_x.$$

## Evolution equations:

$$u_t = v_x + (1 + 2u_x^2)u_x^2 u_{xx},$$

$$v_t = (1 + \beta u_x^2)u_x.$$

Compute local CLs for the coupled model

$$G_{tt} = (\alpha + 3\beta G_x^2) G_{xx} + \eta [2(1 + 4G_x^2) G_x G_{tx} G_{xx} + (1 + 2G_x^2) G_x^2 G_{txx}].$$

- $\alpha = \eta = 1$ .

CL 2:

$$D_t(tu_t - u - t(1 + 2u_x^2)u_x^2u_{xx}) - D_x \left[ \left( t - \left( \frac{1}{3} - \beta t \right) + \frac{2}{5}u_x^4 \right) u_x \right] = 0.$$

- 1 Local Conservation Laws
- 2 Fiber-Reinforced Materials; Governing Equations
- 3 Single Fiber Family, Ansatz 1 – One-Dimensional Shear Waves
- 4 Single Fiber Family, Ansatz 2 – 2D Shear Waves
- 5 Two Fiber Families, Planar Case
- 6 A Viscoelastic Model, Single Fiber Family, 1D Shear Waves
- 7 Discussion**

## Incompressible hyperelastic models

- Fundamental nonlinear equations for finite-amplitude waves are systematically obtained.
- Wave equations derived for one- and two-fiber-family cases.
- Variational structure is inherited in all models.
- Wave breaking in the one-dimensional case.
- Local conservation laws are computed.

## Viscoelastic models

- A one-dimensional finite-amplitude nonlinear wave model is derived, for the two-fiber-family case.
- No wave breaking.
- Local conservation laws are considered.

## Further research

- Consider different geometries of interest for applications (e.g., cylindrical, spherical,...).
- Use the derived local conservation laws for optimization and testing of numerical methods.



Anco, S. C. and Bluman, G. W. (2002)

Direct construction method for conservation laws of partial differential equations. Part I: Examples of conservation law classifications. *Eur. J. Appl. Math.* **13**, 545–566.



Bluman, G.W., Cheviakov, A.F., and Anco, S.C. (2010).

*Applications of Symmetry Methods to Partial Differential Equations.*  
Springer: Applied Mathematical Sciences, Vol. 168.



Cheviakov, A. F. (2007)

GeM software package for computation of symmetries and conservation laws of differential equations. *Comput. Phys. Comm.* **176**, 48–61.



Cheviakov, A. F., Ganghoffer, J.-F., and St. Jean, S. (2015)

Fully nonlinear wave models in fiber-reinforced anisotropic incompressible hyperelastic solids. *Int. J. Nonlin. Mech.* **71**, 8–21.