Analytical properties of nonlinear partial differential equations in shallow water theory and beyond

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Outline

- Euler and Navier-Stokes
- 2 Shallow water models
- Bigher-order and nonlocal models
- Integrability
- 5 Symmetries
- 6 Exact solutions
- Conservation laws
- 8 Hamiltonian and multi-Hamiltonian structure
- Oispersion relations
- Conclusions

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Navier-Stokes equations with forcing

$$\begin{aligned} \rho_t + \operatorname{div}(\rho \mathbf{v}) &= 0, \\ \rho(\mathbf{v}_t + (\mathbf{v} \cdot \nabla)\mathbf{v}) &= -\operatorname{grad} P + \mu \,\Delta \mathbf{v} + \mathbf{M} \end{aligned}$$

Euler equations

$$\rho_t + \operatorname{div} (\rho \mathbf{v}) = 0,$$

$$\rho(\mathbf{v}_t + (\mathbf{v} \cdot \nabla)\mathbf{v}) = -\operatorname{grad} P$$

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Euler equations: formulations and special cases

Euler equations

$$\rho_t + \operatorname{div} (\rho \mathbf{v}) = \mathbf{0},$$

$$\rho(\mathbf{v}_t + (\mathbf{v} \cdot \nabla)\mathbf{v}) = -\operatorname{grad} P$$

Incompressible flows

- Local incompressibility: $\operatorname{div} v = 0$
- Constant density (additional): $\rho = const$

Vorticity formulation

- Vorticity: $\boldsymbol{\omega} = \operatorname{curl} \mathbf{v}$
- Incompressible Euler, vorticity formulation:

 $div \mathbf{v} = \mathbf{0},$ $curl \mathbf{v} = \boldsymbol{\omega},$ $\boldsymbol{\omega}_t + curl (\boldsymbol{\omega} \times \mathbf{v}) = \mathbf{0}$

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Euler equations: formulations and special cases

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Incompressible flows

- Local incompressibility: $\operatorname{div} v = 0$
- Constant density (additional): $\rho = const$

Vorticity-stream function formulation

- Vorticity: $\boldsymbol{\omega} = \operatorname{curl} \mathbf{v}$
- Stream function: $\operatorname{div} \mathbf{v} = \mathbf{0} \rightarrow \mathbf{v} = \operatorname{curl} \boldsymbol{\psi}$
- Euler equations in vorticity-stream function formulation:

$$\operatorname{curl} (\operatorname{curl} \psi) = \omega,$$

 $\omega_t + \operatorname{curl} (\omega imes \operatorname{curl} \psi) = 0$

• Irrotational (potential) flows: $\omega = 0$

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- free surface elevation $\eta(x, t)$
- total fluid depth $h = h(x, t) = h_0 + \eta$
- more generally: variable bottom topography $h_0 = h_0(x)$

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• Euler problem in a water channel with free surface:

$$U_x + W_z = 0$$

$$U_t + UU_x + WU_z = -\frac{1}{\rho}p_x$$

$$W_t + UW_x + WW_z = -\frac{1}{\rho}p_z$$

$$W = 0 \text{ at } z = 0$$

$$W = \eta_t + U\eta_x, \quad p = \rho g \eta \text{ at } z = h(x, t)$$

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- Irrotational case: $\phi = \phi(x, z, t)$, $U = \phi_x$, $W = \phi_z$
- Laplace problem in a time-dependent domain:

$$egin{aligned} \phi_{xx} + \phi_{zz} &= 0\,, & 0 < z < h(x,t) \ \phi_z &= 0 & ext{at } z = 0 \ \eta_t + \phi_x \eta_x - \phi_z &= 0 & ext{at } z = h(x,t) \ \phi_t + rac{1}{2}(\phi_x^2 + \phi_z^2) + g\eta &= 0 & ext{at } z = h(x,t) \end{aligned}$$

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• Small parameters: dispersion parameter $\delta = h_0/\lambda$, amplitude parameter $\varepsilon = A/h_0$

Physical setups:

- Weakly nonlinear, dispersionless: $\delta^2 \ll \varepsilon \ll 1$
- Weakly nonlinear, weakly dispersive: Boussinesq regime $\delta^2 \sim \varepsilon \ll 1$
- Strongly nonlinear, weakly dispersive: $\delta^2 \ll 1$, arepsilon = O(1)

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• Shallow water models are written in terms of dimensionless versions of surface elevation $\eta(x, t)$ and the depth-averaged horizontal velocity

$$u(x,t) = \frac{1}{h(x,t)} \int_0^{h(x,t)} U(x,z,t) \, dz \, .$$

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Non-dimensionalization:

$$t = \frac{\lambda}{c_0} t^*, \qquad x = \lambda x^*, \qquad z = h_0 z^*,$$

$$\eta = A \eta^*, \qquad h = h_0 h^*,$$

$$U = \varepsilon c_0 U^*, \qquad W = \varepsilon \delta c_0 W^*, \qquad u = \varepsilon c_0 u^*,$$

$$\phi = \varepsilon c_0 \lambda \phi^*, \qquad \psi = \varepsilon c_0 h_0 \psi^*, \qquad p = \varepsilon \rho c_0^2 p^*$$

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- Zeroth-order approximation: $\eta_{t^*}^* = -u_{x^*}^* + O(\varepsilon, \delta^2)$, $u_{t^*}^* = -\eta_{x^*}^* + O(\varepsilon, \delta^2)$
- Linear wave equations: $\eta_{tt} \simeq c_0^2 \eta_{xx}$, $u_{tt} \simeq c_0^2 u_{xx}$, $c_0 = \sqrt{gh_0}$
- d'Alembert solution: $\eta^* = F(x^* t^*) + G(x^* + t^*) + O(\varepsilon, \delta^2)$
- Unidirectional right- and left-propagating: $u^* = \eta^* \pm O(\varepsilon, \delta^2)$ (Burn's condition)

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- starred: dimensionless, explicit ε, δ dependence
- canonical: dimensional and/or simplest forms

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• Su-Gardner equations (SG) (also Serre or Green-Naghdi)

$$\begin{aligned} u_{t^*}^* + \varepsilon u^* u_{x^*}^* + \eta_{x^*}^* &= \frac{\delta^2}{3h^*} \left((h^*)^3 \left(u_{x^*t^*}^* + \varepsilon u^* u_{x^*x^*}^* - \varepsilon (u_{x^*}^*)^2 \right) \right)_{x^*} \\ h_{t^*}^* + \varepsilon (h^* u^*)_{x^*} &= 0 \end{aligned}$$

- ε not assumed small; bidirectional waves
- Dimensional:

$$u_t + uu_x + gh_x = \frac{1}{3h} \left(h^3 \left(u_{xt} + uu_{xx} - (u_x)^2 \right) \right)_x$$

$$h_t + (hu)_x = 0$$

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- The Boussinesq equation $\eta_{t^*t^*}^* = \eta_{x^*x^*}^* + \frac{3}{2} \varepsilon \left(\eta^{*2} \right)_{x^*x^*} + \frac{\delta^2}{3} \eta_{x^*x^*x^*x^*}^*$
- \bullet Holds in the Boussinesq regime $\delta^2\sim \varepsilon\ll 1;$ bidirectional waves
- Dimensional version: $\eta_{tt} = c_0^2 \left(\eta + \frac{3}{2} \frac{\eta^2}{h_0} + \frac{1}{3} h_0^2 \eta_{xx} \right)_{ux}$
- Canonical form: $u_{tt} = \alpha u_{xx} + \beta \left(u^2\right)_{xx} + \gamma u_{xxxx}$; S-integrable
- Regularized/ "Bogolubsky" PDE: $u_{tt} = \alpha u_{xx} + \beta (u^2)_{xx} + \gamma u_{xxtt}$ same asymptotic approximation, non-integrable

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- Korteweg-de Vries (KdV) $\eta_{t^*}^* + \eta_{x^*}^* + \frac{3}{2} \varepsilon \eta^* \eta_{x^*}^* + \frac{\delta^2}{6} \eta_{x^*x^*x^*}^* = 0$
- Unidirectional flow; Boussinesq regime
- Canonical form: $u_t + 6uu_x + u_{xxx} = 0$
- S-integrable; multi-soliton solutions

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- Benjamin-Bona-Mahony (BBM) $\eta_{t^*}^* + \eta_{x^*}^* + \frac{3}{2} \varepsilon \eta^* \eta_{x^*}^* \frac{\delta^2}{6} \eta_{x^*x^*t^*}^* = 0$
- Coincides with the KdV in the Boussinesq regime approximation order: $\eta^*_{t^*} = -\eta^*_{x^*} + O(\varepsilon, \delta^2)$
- Canonical form: $u_t + u_x + uu_x u_{xxt} = 0$
- Non-integrable, not Galilei-invariant

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• Kaup-Boussinesq

$$u_t + uu_x + h_x = 0$$
$$h_t + (hu)_x + \beta^2 u_{xxx} = 0$$

• Dimensionless form:

$$\begin{split} \hat{u}_{t^*}^* + \varepsilon \hat{u}^* \hat{u}_{x^*}^* + \eta_{x^*}^* &= 0 \,, \\ \eta_{t^*}^* + \left((1 + \varepsilon \eta^*) \hat{u}^* \right)_{x^*} + \frac{\delta^2}{3} \hat{u}_{x^* x^* x^*}^* &= 0 \end{split}$$

• Bidirectional; Boussinesq regime; S-integrable

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• Shallow water equations

$$u_t + uu_x + h_x = 0$$
$$h_t + (hu)_x = 0$$

• Dimensionless form:

$$u_{t^*}^* + \eta_{x^*}^* + \varepsilon u^* u_{x^*}^* = 0$$

$$h_t^* + (h^* u^*)_{x^*} = 0$$

• Bidirectional; dispersionless regime $\delta \rightarrow 0$; C-integrable

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Where do different SW models come from?

- \bullet Approximation regime: relations between ε and δ
- Order of asymptotic approximation
- Substitutions within the same order, such as $\eta^*_{t^*} = -u^*_{x^*} + O(arepsilon, \delta^2)$
- Use of a velocity variable different from the depth-averaged horizontal velocity

$$u(x,t) = \frac{1}{h(x,t)} \int_0^{h(x,t)} U(x,z,t) dz$$

for example, velocity at a fixed depth: $u(x, t) = U(x, z_0, t)$

• Use of "artificial physics" for PDEs obtained from other considerations, such as integrability requirement, e.g., the Camassa-Holm equation

$$u_t - u_{xxt} + 3uu_x - 2u_xu_{xx} - uu_{xxx} = 0$$

whose derivation was math-motivated

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• The generalized shallow water equation

$$\eta_t + \eta_x - \alpha \eta \eta_t + \beta \eta_x \partial_x^{-1} \eta_t - \eta_{x \times t} = \mathbf{0}$$

with

$$\partial_x^{-1}\eta_t = \int_x^\infty \eta_t(s,t)\,ds$$

• Local (potential) form: $\eta = u_x$,

$$u_{xt} + u_{xx} - \alpha u_x u_{xt} - \beta u_{xx} u_t - u_{xxxt} = 0$$

• S-integrable if and only if $\alpha/\beta=2 \text{ or } \alpha/\beta=1$

• The combined Bona-Chen-Saut-Dullin-Gottwald-Holm system:

$$\begin{split} \tilde{u}_{t^*}^* + \eta_{x^*}^* + \varepsilon \tilde{u}^* \tilde{u}_{x^*}^* + \frac{\delta^2}{2} (\theta^2 - 1) \tilde{u}_{x^*x^*t^*}^* - \delta^2 \sigma^* \eta_{x^*x^*x^*}^* \\ &- \frac{\varepsilon \delta^2}{2} \left(2(\eta^* \tilde{u}_{x^*t^*}^*)_x - (\theta^2 + 1) \tilde{u}_{x^*}^* \tilde{u}_{x^*x^*}^* - (\theta^2 - 1) \tilde{u}^* \tilde{u}_{x^*x^*x^*}^* \right) \\ &+ \frac{5}{24} \, \delta^4 \left(\theta^2 - 1 \right) \left(\theta^2 - \frac{1}{5} \right) \tilde{u}_{x^*x^*x^*x^*t^*}^* = O(\delta^6) \\ \eta_{t^*}^* + \left((1 + \varepsilon \eta^*) \tilde{u}^* \right)_{x^*} + \frac{\delta^2}{2} \left(\theta^2 - \frac{1}{3} \right) \tilde{u}_{x^*x^*x^*x^*}^* + \frac{\varepsilon \delta^2}{2} (\theta^2 - 1) (\eta^* \tilde{u}_{x^*x^*}^*)_{x^*} \\ &+ \frac{5}{24} \, \delta^4 \left(\theta^2 - \frac{1}{5} \right)^2 \tilde{u}_{x^*x^*x^*x^*x^*}^* = O(\delta^6) \end{split}$$

- Nonzero surface tension coefficient σ^{\ast}
- Horizontal velocity \tilde{u} measured at an arbitrary dimensionless elevation $\theta \in [0,1]$ above the flat bottom
- Gives rise to many simpler SW models

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A higher-order model with tension

- A higher-order single-PDE unidirectional version
- Can exclude \tilde{u}^* :

$$\begin{split} \eta_{t^*}^* + \eta_{x^*}^* + \frac{3}{2} \varepsilon \eta^* \eta_{x^*}^* + \frac{\delta^2}{6} (1 - 3\sigma^*) \eta_{x^*x^*x^*}^* - \frac{3}{8} \varepsilon^2 (\eta^*)^2 \eta_{x^*}^* \\ &+ \frac{\varepsilon \delta^2}{24} \left((23 + 15\sigma^*) \eta_{x^*}^* \eta_{x^*x^*}^* + 2(5 - 3\sigma^*) \eta^* \eta_{x^*x^*x^*x^*}^* \right) \\ &+ \frac{\delta^4}{360} (19 - 30\sigma^* - 45(\sigma^*)^2) \eta_{x^*x^*x^*x^*x^*}^* = O(\delta^6) \end{split}$$

• Generalizes the KdV

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- Many definitions, with unclear relationships
- C-integrability
- S-integrability
- Symmetry- and conservation law-integrability: existence of higher-order symmetries and conservation laws.
- Integrability in the Hirota sense: multi-soliton solutions
- Liouville ("complete") integrability: a Hamiltonian PDE system that has an infinite number of conserved densities in pairwise involution. True for bi-Hamiltonian PDE systems
- Formal integrability: existence of a recursion operator
- Painlevé integrability: pass the Painlevé test
- ...

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Related analytical structures

- Lax pairs and zero-curvature representation
- Infinite-parameter and/or higher-order Lie-type symmetries
- Infinite-parameter and/or higher-order local conservation laws
- Painlevé property
- Variational principles and Lagrangian structure
- Hamiltonian and bi-Hamiltonian structure, recursion operators

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C-integrability

C-integrability: "A nonlinear partial differential equation is called C-integrable if it can be solved by a Change of variables"

Example: the shallow water (SW) system

$$u_t + uu_x + gh_x = 0$$
$$h_t + (hu)_x = 0$$

• a point hodograph transformation

$$x = x(h, u),$$
 $t = t(h, u),$ $h(x, t) = h,$ $u(x, t) = u$

• invertible linearization:

$$x_u - u t_u + h t_h = 0$$
$$x_h - u t_h + g t_u = 0$$

Another famous example: the Burgers equation $u_t + uu_x = \nu u_{xx}$

- the Hopf-Cole transformation $u = -2 \nu w_x/w$
- w satisfies the heat equation $w_t = \nu w_{xx}$

S-integrability

S-integrability: "the possibility of construction of solutions of a given PDE system using a Spectral transform technique"

• Main ingredient: a nontrivial Lax pair (L,P), isospectral flow

$$L\Psi = \lambda\Psi, \qquad \Psi_t = P\Psi,$$
$$L_t = [P, L] \equiv PL - LP$$

 \bullet More generally: a zero-curvature representation with matrix operators U,V

$$\hat{\Psi}_x = U\hat{\Psi}, \qquad \hat{\Psi}_t = V\hat{\Psi},$$

 $U_t - V_x + [U, V] = 0$

Main application: exact solutions

- Inverse scattering
- Darboux transformation can be used to iterate solutions
- Multi-soliton solutions through Hirota's bilinear method

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S-integrability

Lax pairs:

- Art or inspiration?
- Existence hinted by other analytical structure (bi-Hamiltonian form, symmetries, etc.)
- May be systematically constructed in WTC/Painlevé analysis

Example: Kaup-Boussinseq model

$$u_t + uu_x + h_x = 0$$
$$h_t + (hu)_x + \frac{1}{4}u_{xxx} = 0$$

• Lax pair:

$$\Psi_{xx} = \left(\lambda^2 - \lambda u - h + \frac{1}{4}u^2\right)\Psi, \qquad \Psi_t = -\left(\lambda + \frac{1}{2}u\right)\Psi_x + \frac{u_x}{4}\Psi$$

• ZCR: $\hat{\Psi}_{x} = \mathrm{U}\hat{\Psi}$, $\hat{\Psi}_{t} = \mathrm{V}\hat{\Psi}$ where

$$\mathbf{U} = \begin{pmatrix} \mathbf{0} & \mathbf{1} \\ \lambda^2 - \lambda u - h + \frac{1}{4}u^2 & \mathbf{0} \end{pmatrix}, \qquad \mathbf{V} = \frac{1}{4} \begin{pmatrix} u_x & -2(u+2\lambda) \\ u_{xx} & -u_x - 2(u+2\lambda) \mathbf{D}_x \end{pmatrix}$$

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- Symmetries are transformations of variables that preserve the solution set of the model
- Point symmetries:

$$(z^*)^i = f^i(z, u; \epsilon) = z^i + \epsilon \xi^i(z, u) + O(\epsilon^2), \qquad i = 1, \dots, n (u^*)^\mu = g^\mu(z, u; \epsilon) = u^\mu + \epsilon \eta^\mu(z, u) + O(\epsilon^2), \qquad \mu = 1, \dots, m$$

• More general: local

$$\begin{aligned} \hat{z}^i &= z^i, \quad i = 1, \dots, n, \\ \hat{u}^\mu &= u^\mu + \epsilon \zeta^\mu [u] + O(\epsilon^2), \quad \mu = 1, \dots, m, \end{aligned}$$

• Infinitesimal generators:

$$\mathbf{X} = \xi^i \, \partial_{z^i} + \eta^\mu \, \partial_{u^\mu} \,, \qquad \hat{\mathbf{X}} = \zeta^\mu[u] \, \partial_{u^\mu} \,.$$

• Lie-type symmetries (and extensions like contact, higher-order, nonlocal, approximate, ...) can be systematically sought using Lie's algorithm

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Some basic one-parameter Lie groups of point symmetries:

 \bullet Translations in space and time, generated by ${\rm X}_1=\partial_x$, ${\rm X}_2=\partial_t$, with global groups

$$\begin{aligned} x^* &= x + \epsilon, \qquad t^* = t, \qquad u^* = u, \\ x^* &= x, \qquad t^* = t + \epsilon, \qquad u^* = u. \end{aligned}$$

• Scaling symmetries, generated by, for example, $X = Ax\partial_x + Bt \partial_t + Cu \partial_u$, where A, B, C are constants, with global group

$$x^* = xe^{A\epsilon}$$
, $t^* = te^{B\epsilon}$, $u^* = ue^{C\epsilon}$.

• The Galilei symmetry, generated by, for example, $X = t \partial_x + \partial_u$, with global group

$$x^* = x + \epsilon t$$
, $t^* = t$, $u^* = u + \epsilon$.

Main applications:

- Construction of invariant reductions, invariant solutions
- Mapping structures such as conservation laws; iterate exact solutions
- Can hint linearizing invertible transformations for C-integrable models
- Eequivalence transforms: mappings relating PDE families, parameter reduction

Symmetry families parameterized by arbitrary functions can lead to invertible linearization (C-integrability)

Example: An infinite-dimensional set of point symmetries of the SW equations

$$\mathbf{X}_{\infty} = \boldsymbol{A} \, \partial_{\mathsf{x}} + \boldsymbol{B} \, \partial_t \, ,$$

where (A, B) = (A(u, h), B(u, h)) is an arbitrary solution of the linear PDE system

$$uA_u + hA_h - (u^2 - gh)B_u = 0$$
, $uB_u - hB_h - A_u = 0$.

Infinite countable hierarchies of higher-order symmetries of increasing order are associated with S-integrability (no guarantees!)

Example: Korteweg-de Vries equation $u_t + 6uu_x + u_{xxx} = 0$:

$$\begin{split} \hat{\mathbf{X}}_i &= K_i \,\partial_u, \qquad K_0 = u_x \,, \qquad K_1 = 6 u u_x + u_{\text{xxx}} \,, \\ K_2 &= 30 u^2 u_x + 20 u_x u_{\text{xx}} + 10 u u_{\text{xxx}} + u_{\text{xxxx}} \,, \end{split}$$

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- 2 Shallow water models
- 3 Higher-order and nonlocal models
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- Symmetry-invariant: e.g., traveling wave u(x, t) = u(x ct)
- Example: Korteweg-de Vries equation $u_t + 6uu_x + u_{xxx} = 0$, single-soliton solution

$$u(x,t)=\frac{a^2}{2}\operatorname{sech}^2\left(\frac{a}{2}(x-x_0-ct)\right)+u_0$$



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- Multi-soliton solutions
- For example, using Hirota's bilinear method



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• Cnoidal traveling waves for Su-Gardner equations

$$u_t + uu_x + gh_x = \frac{1}{3h} (h^3 (u_{xt} + uu_{xx} - (u_x)^2))_x,$$

 $h_t + (hu)_x = 0$



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• Cnoidal traveling waves for Su-Gardner equations

$$u_t + uu_x + gh_x = \frac{1}{3h} \left(h^3 \left(u_{xt} + uu_{xx} - (u_x)^2 \right) \right)_x,$$

$$h_t + (hu)_x = 0$$



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- Solutions using "nonclassical symmetries":
- Example: merging solitons for the generalized shallow water equation

$$\eta_t + \eta_x - \alpha \eta \eta_t + \beta \eta_x \partial_x^{-1} \eta_t - \eta_{xxt} = 0$$



• Weak peakon solutions for the Camassa-Holm equation

$$u_t - u_{xxt} + 3uu_x - 2u_xu_{xx} - uu_{xxx} = 0$$

• A "close encounter" of two peakons



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- Conservation laws provide local and global conserved quantities
- (1+1)-D:

$$\mathrm{D}_t \Theta[u] + \mathrm{D}_x \Phi[u] = 0 \,.$$

• Global quantity:

$$\frac{d}{dt} \mathcal{C}[u] = \frac{d}{dt} \int_a^b \Theta[u] \, dx = -\Phi[u] \Big|_a^b,$$

• Divergence expressions can be systematically obtained using the multiplier method & Euler operators

$$\begin{split} \mathrm{D}_{i} \, Z^{i}[u] &\equiv \Lambda_{\sigma}[u] \, R^{\sigma}[u] = 0, \\ \mathrm{E}_{u^{j}}\left(\Lambda_{\sigma}[u] R^{\sigma}[u]\right) &\equiv 0, \quad j = 1, \dots, m \end{split}$$

Main applications:

- Conservative numerical methods
- Relations to C- and S-integrability
- Relations to symmetries (Noether's theorem)
- A tool to systematically construct nonlocally related (such as potential) PDE systems that lead to new results

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• Example: conservation laws for Su-Gardner equations

$$u_{t^*}^* + \varepsilon u^* u_{x^*}^* + \eta_{x^*}^* = \frac{\delta^2}{3h^*} \left((h^*)^3 \left(u_{x^*t^*}^* + \varepsilon u^* u_{x^*x^*}^* - \varepsilon (u_{x^*}^*)^2 \right) \right)_{x^*} \\ h_{t^*}^* + \varepsilon (h^* u^*)_{x^*} = 0$$

$$\begin{split} \mathrm{D}_t h + \mathrm{D}_x(hu) &= 0 \,, \\ \mathrm{D}_t(hu) + \mathrm{D}_x \left(hu^2 + \frac{1}{2}gh^2 + \frac{1}{3}h^3 \left(u_x^2 - u_{xt} - uu_{xx} \right) \right) &= 0 \,, \\ \mathrm{D}_t \left(\frac{1}{2}h \left(u^2 + gh + \frac{1}{3}h^2 u_x^2 \right) \right) \\ &\quad + \mathrm{D}_x \left(hu \left(\frac{1}{2}u^2 + gh + \frac{1}{2}h^2 u_x^2 - \frac{1}{3}h^2 (u_{xt} + uu_{xx}) \right) \right) = 0 \,, \\ \mathrm{D}_t \left(u - hh_x u_x - \frac{1}{3}h^2 u_{xx} \right) + \mathrm{D}_x \left(\frac{1}{2}u^2 + gh + hh_t u_x + \frac{1}{2}h^2 u_x^2 - \frac{1}{3}h^2 uu_{xx} \right) = 0 \,, \\ \mathrm{D}_t \left(h(t \, u - x) \right) + \mathrm{D}_x \left(h \, u(t \, u - x) + \frac{1}{2}g \, t \, h^2 + \frac{1}{3}t \, h^3 (u_x^2 - u_{xt} - u \, u_{xx}) \right) = 0 \end{split}$$

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Conservation laws

- Example: conservation laws for the KdV $u_t + 6uu_x + u_{xxx} = 0$
- An infinite set of polynomial higher-order CLs related to S-integrability

$$\begin{split} &D_t u + D_x (3u^2 + u_{xx}) = 0, \\ &D_t \left(\frac{1}{2}u^2\right) + D_x \left(2u^3 - \frac{1}{2}u_x^2 + uu_{xx}\right) = 0, \\ &D_t \left(u^3 - \frac{1}{2}u_x^2\right) + D_x \left(\frac{9}{2}u^4 + u_x u_t + 3u^2 u_{xx} + \frac{1}{2}u_{xx}^2\right) = 0, \\ &\vdots \end{split}$$

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• dimensionless Korteweg-de Vries (KdV)

$$\eta_{t^*}^* + \eta_{x^*}^* + \frac{3}{2}\varepsilon \,\eta^* \eta_{x^*}^* + \frac{\delta^2}{6} \,\eta_{x^*x^*x^*}^* = 0$$

• versus Benjamin-Bona-Mahony (BBM):

$$\eta_{t^*}^* + \eta_{x^*}^* + \frac{3}{2}\varepsilon\eta^*\eta_{x^*}^* - \frac{\delta^2}{6}\eta_{x^*x^*t^*}^* = 0$$

- same order of asymptotic approximation!
- KdV is S-integrable; it has an infinite hierarchy of higher-order local CLs
- BBM is not integrable; it has exactly three local CLs

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A Hamiltonian evolution equation:

$$u_t = \mathcal{K}[u] = \mathcal{D} \cdot \frac{\delta H}{\delta u}$$

Main applications:

- Conserved Hamiltonian density, Casimirs
- Hamiltonian version of Noether's theorem
- Bi-Hamiltonian & multi-Hamiltonian structures; recursion operators

A bi-Hamiltonian system:

$$u_t = K_1[u] = \mathcal{D} \cdot \frac{\delta H_1}{\delta u} = \mathcal{E} \cdot \frac{\delta H_0}{\delta u}$$

• Recursion operator:

$$\mathcal{R} = \mathcal{E} \cdot \mathcal{D}^{-1}$$

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• Example: a tri-Hamiltonian structure for the SW system

$$u_t + uu_x + gh_x = 0,$$

$$h_t + (hu)_x = 0$$

$$H_0 = \frac{1}{2} (hu^2 + gh^2), \qquad H_1 = hu, \qquad H_2 = h,$$

$$\mathcal{D}_0 = - \left(\begin{array}{cc} 0 & \mathrm{D}_x \\ \\ \mathrm{D}_x & 0 \end{array} \right), \qquad \mathcal{D}_1 = -\frac{1}{2} \left(\begin{array}{cc} 2g\mathrm{D}_x & u\mathrm{D}_x + u_x \\ \\ u\mathrm{D}_x & h\mathrm{D}_x + \mathrm{D}_x h \end{array} \right),$$

$$\mathcal{D}_2 = - \begin{pmatrix} g(u D_x + D_x u) & \left(\frac{1}{2}u^2 + 2gh\right) D_x + uu_x + gh_x \\ \left(\frac{1}{2}u^2 + 2gh\right) D_x + gh_x & uh D_x + D_x uh \end{pmatrix}$$

• Recursion operators:

$$\mathcal{R}_1 = \mathcal{D}_1 \cdot \mathcal{D}_0^{-1} \,, \qquad \mathcal{R}_2 = \mathcal{D}_2 \cdot \mathcal{D}_0^{-1} \,, \qquad \mathcal{R}_3 = \mathcal{D}_2 \cdot \mathcal{D}_1^{-1} ,$$

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- Stability of equilibrium
- Linearization about $u = u_0(x)$:

$$u^{\mu}(x,t) = u_0^{\mu} + \epsilon u_1^{\mu} e^{i(kx-\omega t)}, \quad \mu = 1\ldots, m,$$

• Dispersion relations:

$$\omega = \omega(k), \qquad c = \frac{\omega}{k} = c(k).$$

- Stability: Im $\omega = 0$ for all k
- Dispersion: linearized waves of different wavelengths travel at different speeds

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• Full water wave problem:

$$\begin{split} \phi_{xx} + \phi_{zz} &= 0, \qquad 0 < z < h(x, t), \\ \phi_z &= 0 \quad \text{at} \quad z = 0, \\ \eta_t + \phi_x \eta_x - \phi_z &= 0, \quad \phi_t + \frac{1}{2}(\phi_x^2 + \phi_z^2) + g\eta = 0 \quad \text{at} \quad z = h(x, t) \end{split}$$

• Perturbation of zero state:

$$h = h_0 + \eta, \qquad \eta = \epsilon \eta_0 e^{i(kx - \omega t)}, \qquad \phi = \epsilon f(z) e^{i(kx - \omega t)}$$

• Dispersion relation:

$$\omega^2 = gk \tanh kh_0, \qquad c = c_0 \sqrt{\frac{\tanh kh_0}{kh_0}}$$

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Dispersion relations

Compare:

• Full water wave dispersion relation:

$$\omega^2 = gk \tanh kh_0, \qquad c = c_0 \sqrt{\frac{\tanh kh_0}{kh_0}}$$

$$\omega = rac{c_0 k}{\sqrt{1 + h_0^2 k^2/3}}, \qquad c = rac{c_0}{\sqrt{1 + h_0^2 k^2/3}}$$

• KdV:

$$\omega = c_0 k \left(1 - \frac{1}{6} h_0^2 k^2 \right), \qquad c = c_0 \left(1 - \frac{1}{6} h_0^2 k^2 \right)$$

• BBM:

$$\omega = rac{c_0 k}{1 + h_0^2 k^2/6} \,, \qquad c = rac{c_0}{1 + h_0^2 k^2/6}$$

• SW: $c \neq c(k)$ so no dispersion

$$\omega^2 = c_0^2 k^2, \qquad c = c_0 = \sqrt{gh_0}$$

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A diagram of physical relations between some shallow water models:



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Arnold's principle

If a model bears a name, it is not the name of the person who discovered it

Examples:

- Korteweg-de Vries \rightarrow Boussinesq (25 years earlier)
- Su-Gardner (Green-Naghdi) \rightarrow Serre (13 and 21 years earlier)
- Camassa-Holm \rightarrow Fokas and Fuchssteiner (12 years earlier)

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Too many things left out...

- Variational/Lagrangian structure: self-adjointness of linearization
- Painlevé property: all linear equations pass; related to integrability; Camassa-Holm as counterexample
- Solution existence, uniqueness, stability
- Numerical aspects
- MANY extended PDE models
- Multi-dimensional versions
- ... and more ...

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Thank you for your attention!

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